

Article

Roads to Consciousness: Crucial Steps in Mental Development (Part I)

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Abstract

This contribution explains several “roads to self-awareness”, all of them based on the natural sciences. The first one follows our bio-psychological evolution. The second road starts with the engineer’s point of view and mainly builds on information science and technology, in particular robotics. The third road taken is the most abstract - It exploits complex dynamic systems and their emergent properties. Despite their different origins and methods, these lines of investigation converge. That is, the findings of various fields can be combined into a unified theory of mind and self-awareness, which is the main purpose of this paper. This overall synthesis suggests that the mind results from a multi-hierarchical organizational structure, and self-reflexive flows of information in embodied systems. In addition to this, stable self-awareness appears spontaneously in sufficiently complex robots, when the system’s capability of describing itself crosses the level of conceptually clear information processing (thinking). As an application, one obtains a number of construction principles for mentally developing systems that are explained towards the end of this contribution.

Part I of this four-part Article includes: 1. A Psychobiological Theory of Self-awareness.

Keywords: Self-consciousness, self-awareness, free will, dynamic systems, hierarchical systems, language.

1. A Psychobiological Theory of Self-awareness

It’s the brain in a body in a world that matters (Smith 2009)

In a sense, much of the reasoning of the first section is well-known. However, it is one thing to be aware of some relevant components and steps to be taken. It is quite another to assemble these pieces into a logically-sound blueprint of an extremely complex machine.

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Step 1: Information processing. The most important property of (animal) nervous systems is that they process information. The incoming information, the input of the system, stems from the outside world. This input may be stored and internally processed in many ways. Often, the stimuli have to be transformed into behavioural responses that are adequate with respect to the momentary situation.

In a nutshell, stimuli are processed somehow in order to reach some behavioural response. This Stimulus-Organism-Response paradigm is a classic, introduced by behaviouristic psychology about one hundred years ago (Watson 1913). Since a classic computational device reads input, processes it, and produces an output, “S-O-R” (“Input-Process-Output”) is also the most fundamental model of information processing in the computer sciences.

Step 2: Representation. In order to produce reasonable motor actions, the brain needs to represent relevant parts of the external world. These representations are based on the input provided by the sense organs, and every sense organ is associated with typical units or items: touches, smells, tastes, sounds, and, of course, images. The items may be stored and retrieved from an internal memory or be evoked by some external stimulus. But these are details. The point is that, altogether, they constitute a (possibly very crude) model of the world which, despite all the interrelations amongst the items, must be based heavily on sensory input if it is to be of any value to the individual. For human beings, images are by far the most important representations.

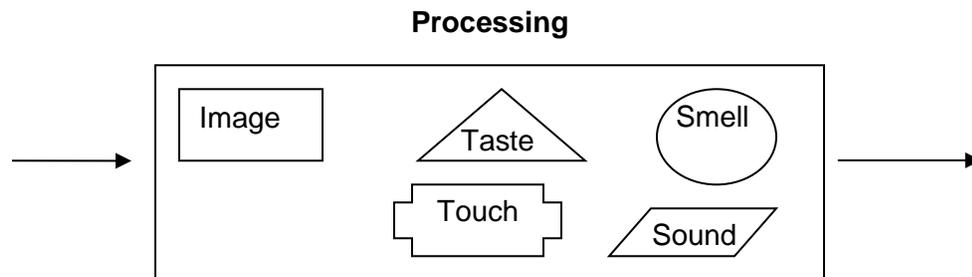


Illustration II (Various internal representations, e.g., of a single external object)

Contemporary scientists face a similar problem: If a robot is to accomplish some task, it first of all needs to be informed about (relevant aspects) of its environment. Thus a crucial question becomes how to represent or “model” the external world in the robot.

Step 3: Integration. Given some external object, this object is perceived by various sense organs: An observer sees a cup of coffee, smells its odour, recognises its temperature, and tastes the characteristic flavour. All these bits of information, transmitted by various channels – to use modern jargon – need to be integrated into a comprehensive and single impression: a fine cup of coffee, or, more precisely, the cup of coffee as you perceive it. Gestalt psychology stressed the necessity of integration with respect to visual perception; but also many contemporary authors emphasize that diverse sensory impressions need to be combined. Damasio (2010) calls the integrated chunks of information a “map”. In a chapter entitled “Putting it together”, he highlights the role of the brain stem in this endeavour.

Step 4: Representation of own body. There are not just sensory impressions of the external objects. The mental realm also contains representation(s) of the animal's physical body or body parts. These special items are rather easy to obtain, since all input information is associated with sense organs that are embedded in the physical body.

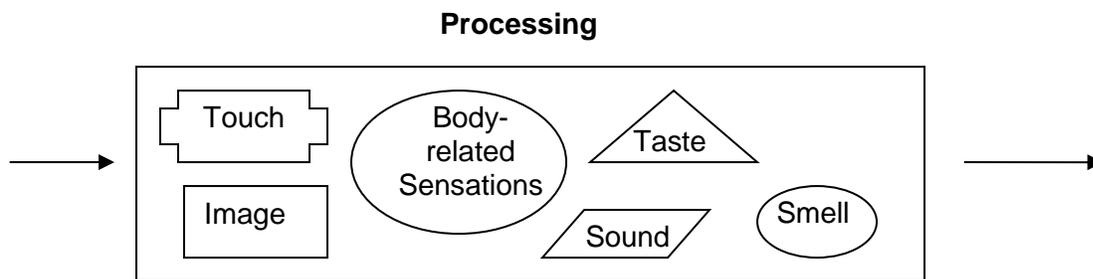


Illustration I2 (Internal representation of body parts or body-related phenomena)

Given this, there is (at least, at first) not much special about one's own body. Various sensory impressions are combined into one mental entity, typically called a body image (cf. Gallagher 2006, De Preester and Knockaert 2005). In other words, any animal or robot, possessing a body and equipped with sensory organs is able to perceive its own body and may thus form a comprehensive body image. But although, in a sense, it is a map like any other map, there is something peculiar about it. You perceive your own body from a unique perspective. Owing to your viewpoint, you see at least parts of it, e.g., your arms, chest, belly, legs and feet. Recognizing your own voice may even be easier than listening to others. Moreover, this – your - (integrated) body map takes centre stage.

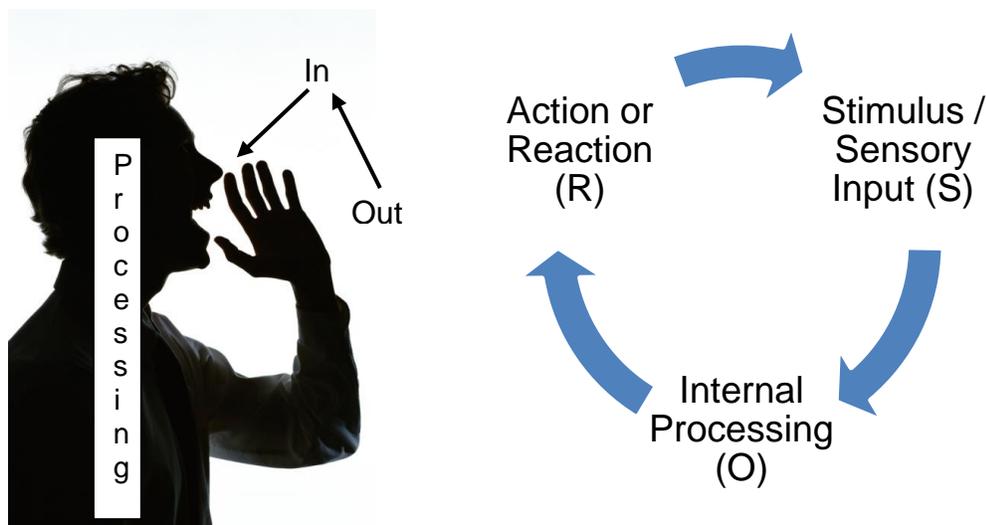


Illustration I3 (Circular Information Processing: – the sensorimotor loop)

Step 5: Circularity. On the one hand, it is the body which is receiving external information. On the other hand, the body is acting in the outside world. Therefore, things start to become circular here: The individual takes action in the real world, causing some change there, which subsequently - within hours, minutes, or seconds - may have some noticeable consequence. In other words, for every animal but also every human being and every robot, anything takes place around a centre which is the personal body (being agent as well as observer).

For this situation, computer scientists coined the term “embodied cognition”, and placed it in stark contrast to traditional artificial intelligence (AI): “Instead of emphasizing formal operations on abstract symbols, the new approach...foregrounds the fact that cognition is a highly *embodied* or *situated activity*..., and suggests that thinking beings ought therefore be considered first and foremost as acting beings” (Anderson 2003, p. 91, italics in the original). “Grounded cognition” is also a prominent new concept in psychology: “[It] rejects traditional views that cognition is computation on amodal symbols in a modular system, independent of the brain’s modal system for perception, action, and introspection” (Barsalou 2008).

With the “sensorimotor loop” (Der & Martius 2012) or “perception-action” loop (Shapiro 2010) in place, perceptions are always related to the body, which subsequently may take suitable, i.e., input-dependent actions (S-O-R). Starting with motor actions, they and their consequences can be perceived and may have some impact on the body (R-S-O). Finally, it is only the body that can take action and perceive what has happened (O-R-S).

Various iterations of the loop (S-O-R-S-O-R-...) reveal that there is something special about the body (O): It does not just take centre stage with respect to perceiving (it has a unique

perspective), it also takes centre stage with respect to acting – its “effectors”, i.e., its hands, feet etc., change the environment. Using this loop effectively means learning what consequences an action has, i.e., an inept beginner may evolve into an adept master. Subsequently the processing within the body may choose a certain action in order to provoke a certain effect on the body.

Accordingly, science nowadays distinguishes between the (integrated) body image which is mainly sensory, the (complete) body schema which is both sensory and motoric, and agency which is mainly motoric (De Preester and Knockaert 2005). But, of course, all these entities are intensely linked. In humans, precise hand-eye coordination is nothing but a tight feedback loop of the above kind: We embark on a certain action, observe intermediate results, may thus alter our (re)actions, until, finally, we obtain a desired result involving some external object or one’s own body. Obviously, there are many feedback loops around, involving other effectors and sense modalities. Moreover, internal feedback loops within the brain seem very likely. We may thus simulate a certain action and anticipate its results without actually performing it in the real world.

Step 6: Self-perception. The crux of the Chinese room argument (Searle 1980) is that the room (or anybody in it) does not know what is really going on: Received input is merely transformed into output in a perfect way. The machinery has no concept, no map or token for itself. With the flow of information changing drastically, and the body becoming a major player, the situation is completely different, and qualitatively new “emergent” phenomena become likely.

If action and perception are closely related, e.g., if the animal's (own) body is acting and - almost at the same time - the animal perceives that the body (located in the centre of activity, and being of paramount importance) is in motion, it is a small step to assume that the animal “notices” itself. That is, it observes that there is something special about this body; that a distinction should be made between oneself and the rest of the world. As human beings rely mostly on the visual sense, the perceived image of the own body is by far the most important representation of oneself.

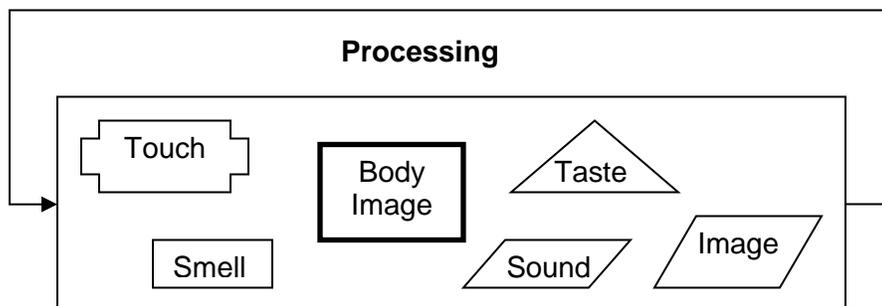


Illustration I4 (An accentuated image/representation of the body emerges)

Due to the circular situation, the body plays a double role. It is a (rather) passive object being perceived and (its map) being processed. At the same time, it is the active subject, acting in the external world. On the one hand, just like any other object, the body is perceived by the sensory organs, and represented by a cognitive, i.e., internal map. On the other hand, the body's nervous system, in particular its brain, is doing all this processing. That's a very peculiar and unique property, distinguishing the body and its (mental) activity from all the other objects around.

All perceptual as well as motoric information is linked to the brain. More precisely: Within the flow of information coming from the senses and finally resulting in motor actions resides "central processing". The brain's mental transformations are an integral part of the complete situation, or – rather - a pivotal element of/in the sensorimotor loop. Now, if feedback is strong and rather instantaneous, i.e., if the various perception-action loops are tight and numerous, the body and its mental processes can hardly escape their own presence. Thus a straightforward question arises: How much do they "notice" their own activities? Or, to put the question slightly differently: How much does a body endowed with an information processing unit understand about its status, i.e., the role it plays in the above situation? In particular, is it able to distinguish between private and external, self vs. context?

Obviously, the answer to the latter question forms a **continuum**, the continuum of self-awareness. One extreme consists of beings (be they living or artificial) without the slightest idea about themselves. The other extreme shows up in healthy, grown-up humans who know exactly where they are and what they are doing. In between seem to be animals (and perhaps robots) that - more or less - understand their situatedness. Depending on their "equipment" (both mentally and physically) they approximate the "human end" of the continuum of self-awareness to varying degrees. However, since complex life forms originated more than half a billion years ago and humans are the only conscious species we know, it also seems to be very difficult to overcome obscurity, and to reach the "enlightened" endpoint. Thus a straightforward question is which powerful tool(s) enabled man to get there.

Step 7: Language. The crucial innovation of homo sapiens is an effective, omnipresent language. With the naming of objects, the verbal description of facts and the narrative planning of actions, a second, language-based internal representation (i.e., model) of the real world evolves. Although the verbal model is strongly connected with the first (mainly visual) representation of the world, the individual has **two** distinct ways to realize things. Typically, two representations of one and the same fact are available – an *image* and a *name*. A concept is just this: Some sensory impression plus a corresponding verbal description (de Saussure 1907).

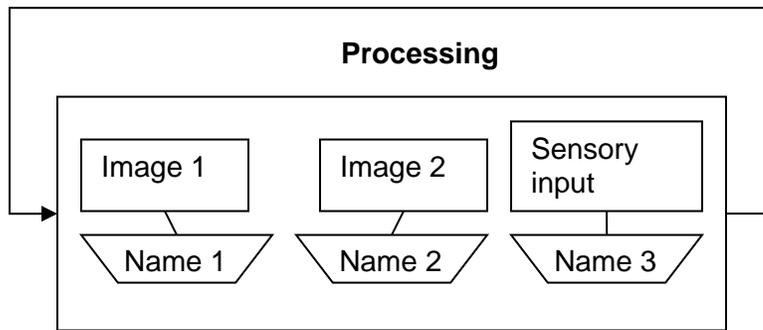


Illustration I5 (Concept formation. Concept = word plus meaning)

With language comes conceptual precision and clarity. One may systematically name objects and delineate a situation. Whereas maps are located on the perceptual “side” of the sensorimotor loop, speech production is an active feature, rather located on the motor “side”. Thus language immensely helps in describing, analysing, and moving in the world we inhabit. It makes way for a deeper understanding of our natural and social environment, our place in it, and our personal characteristics - be they external (such as the expression on my face) or internal (e.g., the mood I am in).

To cut a long story short, many scientists and philosophers think that our exclusive language skills make the difference (e.g. Deacon 1997, Arbib 2001 & 2014, Hauser et al. 2002): As an extremely versatile and powerful tool, language is the single most important disparity between man and animals (even the most developed ones). It seems to be no coincidence that those animals considered closest to us (in particular certain primates, whales and birds) have remarkable language competences. Moreover, it has been reported that people who learned language late in their lives refer to themselves as some “phantom” that existed before. See, for example, the “extraordinary mind of Helen Keller” in Donald (2002, Chapter 6), and Schaller (1991).

Step 8: A special image and a peculiar name. In particular, perception and language yield two distinct representations of the subject. There is a nonverbal and a verbal description of oneself available: the image of the body – which already has had an accentuated position - and its (specific) name. Body and name are not like all the other objects, there is something special about them, for word and image – both - represent the individual.

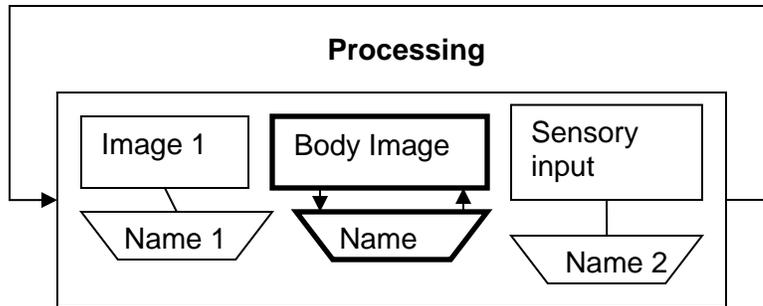


Illustration I6 (The Self-Concept = Body Image & corresponding name)

Since the purpose of our most important sense organs is to collect information about the outside world, these organs are directed away from us. However, when we look into a mirror the view is thrown back. I see my own body and my face, a peculiar part of my body, distinguishing myself from everybody else in the world. It is surely no coincidence that, with the help of this strong and immediate visual feedback, at least some animals of a few species are able to recognize themselves (Gallup 1970). They notice that the body and face they encounter are something special, that this impression differs from all other objects. (For an up-to-date overview of the species passing the “mirror test” cf. the entry bearing the same name in the English wikipedia.)

In other words, with the help of the mirror’s immediate feedback, there is an additional loop, and the mental processes in an animal’s body are able to distinguish between own and alien. That is, in front of a mirror, the animal - or rather its information processing - is able to draw a (cognitive) line between its individual existence and the rest of the world. In this sense, the mirror acts as a catalyst towards self-awareness. However, if these animals look in a different direction, the loop is gone and they seem to lose their fundamental insight almost immediately.

With our sense organs intact, humans - but also our cousins in the animal kingdom - perceive a rich model of the real world. That is, without any effort, we all observe what is going on around us. Homo sapiens, however, is the only species that is able to describe the situation in a second, completely different way. The crucial point seems to be that humans with a versatile, powerful language system possess a second (verbal) tier and thus a fully functional “internal mirror”.

Step 9: Self-Awareness. Already within the perceptual model alone, there is a special entity: the body. Since it is the central unit, all action taking place around it, and observation being directed towards it, it plays the primary-role.

In the world of language all kinds of objects and phenomena are given names. Here, too, evolves a concept with a special meaning. It is the concept that names the individual’s body and anything

directly related to it, such as the visual appearance, the sound of the voice, actions initiated by the body, and internal states.

From the very beginning of verbal utterances, the body map and the word used for myself are close. For what is the meaning of the latter concept? Its semantics are always very much related to the body's perspective, its parts, its actions, and, last but not least, the mental operations going on within the very head of this body. When processing words and sensations, the body image is reflected in its corresponding name and the name has a counterpart in the corresponding body image.

Something extraordinary happens when these parts, two different representations for the same "thing", melt into a single unit. Image and name combined constitute a concept of oneself (or one's self, respectively). This concept ("I" / "me") is very different from all other concepts: It describes the centre of existence, the source of actions and the spot where all perceptual input converges. In the verbal realm, everything that is going on "revolves" around this crucial token.

The entity that emerges is a self-concept of the individual, and the individual becomes self-conscious, i.e., fully aware of its position in the world. Identifying the body's name with the body's image is the crucial step that yields the self: an entity in the middle of everything, right at the centre of action and sensation, yet distinctively different from anything else in the world, and of paramount importance.

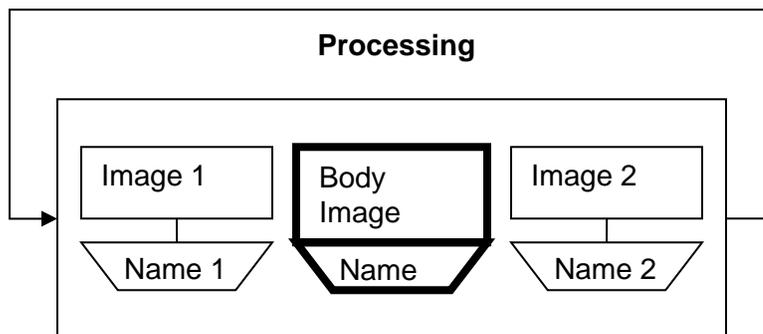


Illustration I7 (In the mental realm, clear self-awareness is the result of a crisp, stable distinction between the body concept and anything else)

Since step #9 is crucial, let us describe it once again from a more abstract point of view: Animals of all species possess at most one elaborated perceptual model. Some, like dolphins, use complex communication systems in addition. However, homo sapiens seem to be the only species with two very rich systems of description. Although they are closely related, they exist in their own right, and there is a pronounced difference between the world as we perceive it and the world we are talking about. An image and a concept are completely different chunks of information.

Animals need the help of an external mirror to encounter themselves. With a rich perceptual as well as a sophisticated verbal model, that's different: Each of these models can serve as an "internal mirror" to the other. Moreover, both include a marked representation of oneself: the body map on the one hand, and a peculiar word for the individual on the other. In other words, the reflection of the concept "I" is the body map; and the body image is represented by the term "I" in the realm of language.

This internal feedback loop is immediate, tight and strong. In order to reach a clear understanding of oneself, all that is still needed is the identification of word and map, of a peculiar name and its visual image. When these two objects fuse, a comprehensive concept emerges, encompassing all properties belonging to the extraordinary entity right at the centre of everything that is going on. On the one hand, the chunk of information standing for oneself is body-related (all we sense, feel, think and do at a certain moment in time); on the other hand, it is a clear-cut, precise concept. On the one hand, it is passive/receptive (e.g., the image we see in a mirror upon opening our eyes), on the other it is active/motorial (e.g., planning, volition, and taking action). Thus a personal self is born, one's very identity established.

One could also say that the personal self comes into existence due to a permanent, stable distinction between oneself (or: one's self) and anything else. Learning the distinction between own and alien is considered crucial in developmental psychology. Rochat (2003) writes [italics in the original]: "Until the middle of the second year when linguistic and symbolic competencies start to play a major role in the psychic life of children, self-awareness remains *implicit*. It is expressed in perception and action, not yet expressed via symbolic means such as words. Prior to approximately 14–18 months there is yet no clear evidence that the children perceive traces of themselves, as *standing for* themselves, only themselves, and no one else, such as the little footprints they might leave in the mud or the image they see in the mirror." He calls the crucial step "identification": "At this level, the individual manifests recognition, the fact that what is in the mirror is 'Me,' not another individual staring and shadowing the self."

In other words (Saint-Mont 2001): Self-awareness emerges when we learn to draw a clear-cut cognitive line between us and the rest of the (perceived) world. It is this *permanent, stable distinction* which constitutes personal awareness (see the last and the next illustrations). We are self-conscious beings, aware of our individuality, because of a stable contrast between a world "out there" and ourselves (or "our selves", respectively)

Yet another way to express the step to self-awareness is to say that we are no longer strangers to ourselves. Instead of looking at ourselves from the outside, always with a certain distance, we understand that we are both the one perceiving and the one being perceived, that we are acting and, at the same time, observing what we are doing. Listening while we are speaking triggers the

insights that (1) speaker and listener are the same person, and (2) that we are trying to understand our own words, not somebody else's. In a nutshell, we come into our own, distinguish our identity from all others, and recognize our self (or: ourself) in a clear, conceptual way.

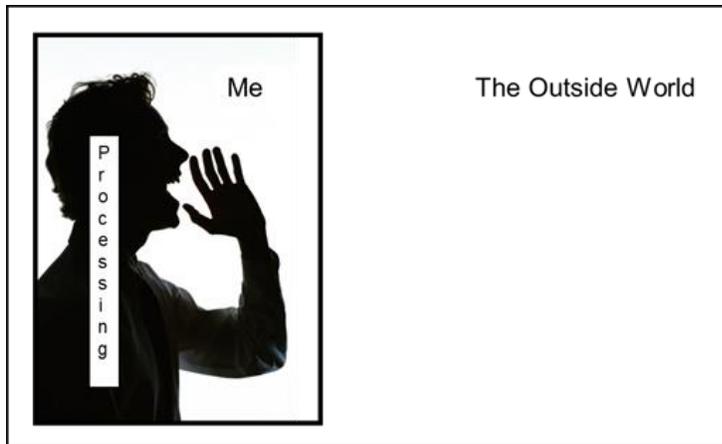


Illustration I8 (Given a person and their environment, conceptually clear self-awareness distinguishes oneself - one's self - from anything else)

This step is crucial, since we thereby reach the “enlightened” end of the mental continuum. The centre of all perception and activity leaves vagueness behind, the human agent reaches a completely new level of insight – the cognitive level. (“Cognitive” meant in a narrow verbal-conceptual sense; as opposed to imprecise emotions, multifaceted perceptions, not integrated lines of information processing, and a fuzzy perforated boundary between “inside” and “outside”, oneself and others.) That is, man finally understands the basic setup of the game and his distinguished role in it. Upon integrating all individual-related information into one conceptual entity, he forms an identity. Equivalently, one could say that upon establishing a stable frontier between own and alien the personal identity is assembled. The boundary is mainly conceptual and it is fundamental to all cognitive processes, since it creates a precisely defined “me”. So, equivocally speaking, “self comes to mind” (Damasio 2012), whereas, before, there was just “the feeling of what happens” (Damasio 1999).

Step 10: Major consequences

The steps taken seem to be straightforward. In particular, I described the last, crucial step as if it appeared all of a sudden, in a certain moment of “enlightenment”. Of course, in a certain sense, establishing a self is like picking a ripe fruit from the tree of knowledge. However, in the physical world, developments take time. First, it is well-known that new-borns need many months to develop the mental capacities necessary, in particular language skills, for them to finally reach their selves. Second, the crucial insight may appear all of sudden, but it may also be

forgotten in a minute. Therefore, third, it takes months until the “Me-But-Not-Me dilemma” (Rochat 2003) is finally dissolved, i.e., a stable individual identity endowed with clear self-awareness is established.

Fascinating as these developmental details may be, even more important is the reorganization of the psychological arena that occurs subsequently. With a perceiving and acting agent in the middle, perfectly aware of its position in the world, the information flow is altered dramatically. The self “coming to mind” triggers a *fundamental reorganization of the mental landscape* and completely new effects emerge:

1. Thinking becomes conceptually clear
2. Planning is thus rendered deeper and more complex
3. Subsequent actions taken are better-aimed
4. Attention steers the sensors towards the most interesting phenomena
5. Externally, individuals can quite systematically explore their whereabouts
6. Internally, they may explore their mental lives (feelings, preferences, traits, etc.)
7. Thus they gain a much deeper understanding of their status and development
8. Memory can become more selective, saving important information first
9. An extended self-view with an extensive autobiographical memory occurs
10. A sense of property emerges (all things that belong to me, but not to others)

Altogether, step by step, these abilities potentiate the individual’s reach, and, make no mistake, it is the developing agent that is actively extending its force. There is an owner who learns to handle the mental and physical tools available, and, in the end, can apply them as he / she pleases. Fortunately for us, it turns out that human brains are embedded into a versatile body with an appropriate size, and well-functioning in almost any natural environment, on land as well as in water. Even more important is the fact that we are able to design, to change our environment with the help of very sophisticated effectors: our hands (Wilson 1998). That’s a lucky coincidence, since self-awareness could also be “locked” in a body tailored to a narrow ecological niche; just suppose you were a raven, a dolphin or an elephant...

On their own, individuals can survive: they can assemble tools and equipment, hunt, produce clothing, and may even build a hut. However, many hands and brains, working together, are needed to piece together megalithic sites, pyramids, or walls stretching thousands of miles. With the help of language, writing and many more cultural techniques, man has been able to organize larger, work-sharing, stable groups that turned out to be the nucleus of complex societies. Nowadays, this historic quest seems to be cumulating in one truly global culture.

Impressive as all these steps are, we have omitted the single most important one, occurring quite early and adding a completely new dimension to our cognitive lives. This single most important

personal insight is the detection of time. Unlike all animal species, we do not just live in three-dimensional space: Looking back, we see that we were younger, with people telling stories about our birth, when our subjective life started. Looking ahead, however, each and every one of us has to concede that we are growing older, until finally, our lives are over. Understanding the past, and foreseeing at least a part of the future is an invaluable gift, it deepens and widens our consciousness immensely. However, this gift inevitably comes with knowledge about our inevitable fate. Each and every one of us must foresee and thus face the fact of death, i.e., a limited existence in time.

Consciousness has been a great invention, perhaps it has been the most powerful innovation ever since the Cambrian explosion (Cowen 2013), reaching a completely new level of insight and complexity, shaping much of us (our culture, and history), and altering the face of the planet. Nevertheless, self-awareness - in essence a mental borderline - comes with restrictions and limits: Opening one's eyes in the middle of the night won't make the sun shine, since the sensory system and the view of the world it provides are not affected by cognitions.

In more general terms, consciousness is a higher-level mental process with a certain influence. However, this process neither understands nor controls our psycho-physiological machinery completely. Freud and many others have pointed out that major mental tokens, like motivation, emotions, drive, pleasure or pain are beyond its reach. There is both voluntary and involuntary motor function. Moreover, everybody is born with a certain set of physical and mental properties. These properties constitute basic conditions under which our lives evolve. (It really makes a difference if one is blind or keen-eyed, emotionally stable or fragile, can move their limbs or not.) Although we are able to talk about almost anything, we are clearly aware of much and we are able to change some conditions, there are always many boundary conditions that we may neither oversee, nor understand, nor are able to alter.

So, finally, there we are: A well-defined identity with a distinct personality, precisely knowing where it is located in time and "space" (the latter being physical and social). In all the fields described, our boundaries have widened. However, inevitably, our psychological life is tied to a particular body. Instead of being like a "spirit hovering above the waters", we are "embedded intelligence", inseparably linked to some physical entity, to the extent of being this body's agent.

(Continued on Part II)

Article

Roads to Consciousness: Crucial Steps in Mental Development (Part II)

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Abstract

This contribution explains several “roads to self-awareness”, all of them based on the natural sciences. The first one follows our bio-psychological evolution. The second road starts with the engineer’s point of view and mainly builds on information science and technology, in particular robotics. The third road taken is the most abstract - It exploits complex dynamic systems and their emergent properties. Despite their different origins and methods, these lines of investigation converge. That is, the findings of various fields can be combined into a unified theory of mind and self-awareness, which is the main purpose of this paper. This overall synthesis suggests that the mind results from a multi-hierarchical organizational structure, and self-reflexive flows of information in embodied systems. In addition to this, stable self-awareness appears spontaneously in sufficiently complex robots, when the system’s capability of describing itself crosses the level of conceptually clear information processing (thinking). As an application, one obtains a number of construction principles for mentally developing systems that are explained towards the end of this contribution.

Part II of this four-part Article includes: 2. The Technical Perspective.

Keywords: Self-consciousness, self-awareness, free will, dynamic systems, hierarchical systems, language.

2. The Technical Perspective

What I cannot create, I do not understand (Feynman 1988)

Although the arguments so far have focused on human onto- and phylogenesis, they can also be understood in much more general terms. In a sense, it would be very surprising if homo sapiens could be the only self-conscious system or if biological details were decisive. Thus, although the above steps mainly used psychological and biological concepts, given a detailed enough blueprint, containing all crucial technical details, one should be able to construct conscious

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systems - planes fly since we have understood the physics, not because we imitate birds perfectly.

The state of the art

How far have we come with this endeavour, what's the state of our art? We know how to build computers. More generally, we have learned to construct fast, reliable and competitive hardware. For example, although the capacity of the human memory is incredibly large, cutting-edge technical storage devices have reached the same capacity. In other areas, in particular speed, modern semi-conductor micro-technology has already left its biological counterparts far behind.

With respect to software we know how to “knit” programs, we are able to create flexible modules, we can manage multi-tier architectures of considerable size, and there is even a stable network connecting millions of devices worldwide. In other words, software-engineering is much less of an art than it was decades ago. Nowadays, it is a routine task to design, to implement and to run large powerful IT systems.

Despite such impressive technological developments, progress in the field we are interested in has been rather slow. From their very beginnings in the 1950s, traditional artificial intelligence and cognitivist approaches placed great emphasis on symbolic manipulation, modelling, and planning. In other words, “out of a soup of ideas on how to build intelligent machines the disembodied and non-situated approach of problem-solving search systems emerged as dominant” (Brooks 1999, p. 146). That is, countless and often very elaborate programs were written, trying to mimic man's extraordinary cognitive abilities. Yet when built into machines, they only succeeded in very restricted situations (like chess); everyday situations that are both fuzzy and complex, have remained a mystery to any machine. For an instructive overview see Vernon (2010) and Shapiro (2010).

Step 1: Robots

Looking at the problem of self-awareness through an engineer's eyes, we are ultimately interested in artificial consciousness in the sense that the organization of a machine and its corresponding flow of information yields personal self-awareness. Because of the arguments outlined above, it seems wise not to begin with a computer, equipped with the best hardware and the most elaborate software available, but rather with a robot, the latter being much closer to the biological starting point that led to consciousness in the natural world.

A robot is a machine of a special kind: It has a body equipped with sensory and motoric devices, and it is **situated** in a certain environment. Since it is to act without the help of a foreign centre of control, it also needs an embodied “CPU” (a brain) that does most of the information

processing necessary. As already mentioned, although these ideas are rather straightforward, this “agentic approach”, focusing on mobile robotics has needed several decades to gain ground (Barsalou 2008).

Typically, a robot is designed towards a goal. For example, if an animal wants to proliferate, it must survive for a certain amount of time and in order to do so it needs to gather food. Suppose its energy supply comes from a particular plant. Thus its task is to detect this plant and move its body toward it. Note, that this “feeding behavior” will only be successful if the sensory stimuli and the motor (re)actions are associated in the right way, i.e., if the program linking sensory input to behavioral output is able to guarantee sufficient food supply.

Step 2: Appropriate software

In total generality, one may think of a program that steers a body (O), i.e., that connects the input stimuli (S) with some behavioural response (R). There may be much processing going on in between, many stimuli might not lead to any action at all, and it could be very difficult to understand how an action came about or how stimuli, reactions and internal information processing are inter-related. Moreover, the sensorimotor program can be implicit, in particular hard-wired into the structure of a neural net, or it can be rather explicit, e.g., a long list of IF – THEN – statements, the IF-part containing all kinds of (external and internal) stimuli, the THEN-part containing all kinds of (external and internal) responses. However, whatever the details, the fundamental task and thus the basic solution are equivalent to both: natural and artificial systems. There is a certain body, situated in a particular environment that needs to be able to process information, turning relevant stimuli into adequate motoric output. Thus, in order to survive, it has to collect data, draw conclusions, and act appropriately.

Following the path of evolution, in primitive animals, there only seem to be a few fixed lines of code. That is, the sense organs are primitive, and the behavioural repertoire is very limited. As is the program connecting the two: certain stimuli will lead to foreseeable answers. Biologists call such a situation (behavioural) imprinting. Once an animal has adopted a certain behaviour it will display it over again and it is not able to change it. Searle’s Chinese room is quite similar: A rather complex but fixed program receives questions in Chinese and answers them appropriately.

In other words, without further provisions, an animal or robot equipped with a constant program cannot learn. It is restricted to a possibly large, but fixed, way to perceive and to act upon its environment. Thus, every day, millions of moths die in flames since their program instructs them to approach bright lights, and countless generations of singing birds have been raising cuckoos, falling prey to the irresistible red colour of the parasite’s throat.

Being able to learn is tantamount to saying that the sensor-motoric program possesses some *plasticity*. The program code – be it implicit or explicit - is not fixed (write-protected or closed) but open, subject to change. In the simplest case, a stimulus-response relation may be altered, i.e., an existing line of the program can (be) change(d). In particular, some stimulus may cause a different response than before, or a certain response may be the consequence of a new stimulus. More advanced cases would be existing lines being deleted, or new lines being added to the program.

Because the program resides in a body, located in an environment, there is also some *circularity*. Unlike a computer program, whose input and output are distinct, only connected by the program, the behaviour of the body may serve as the system's *input* in the next period of time. A response can become a stimulus, and the more often and the faster this happens, the more pronounced the feedback loop. Weng (2009) points out that a system's output need not only consist in overt external behaviour, there could also be "internal effectors" working within the body. Moreover, external sensors can be supplemented with internal sensors, again strengthening feedback.

In total, there are a number of ways - chains of events - via which a program within a body may act on itself: It may, rather indirectly, affect its environment which later on has some consequences for itself (think of an echo in the mountains), it may, in a more direct manner, change the state of the body, which subsequently influences the mental state (think of alcoholic beverages). Yet the mind could also have a direct impact on internal affairs without the help of external feedback loops. For example, sombre thoughts may result in an emotional reaction, e.g., depression, whereas some meditation may evoke positive thoughts. Finally, the program may act directly on itself. Some output may, without other 'stations' being involved, directly act as its next input. Moreover, it may even happen that some line of the (open) program is actually writing the next line to be processed.

Step 3: Multi-layered systems

Let us look at the program, connecting input and output, in more detail: It is located within the body, the information flows through it, connecting sensory input and effective output. In this sense, it is the centre of all sensations and actions, and its aim is to steer the body successfully in the outside world. Thus a fully developed program should consist of several distinguishable parts: a sensory part, dealing with the incoming information; a second part, analysing, integrating and drawing conclusions from the data; and a third part, responsible for the actions. In order to survive, the sensory part should not be a muddle of sensations, but should supply the individual with a well-ordered model of the world, within which the body is located. Moreover, some planning has to result in actions (cf. Brooks 1999: 4):

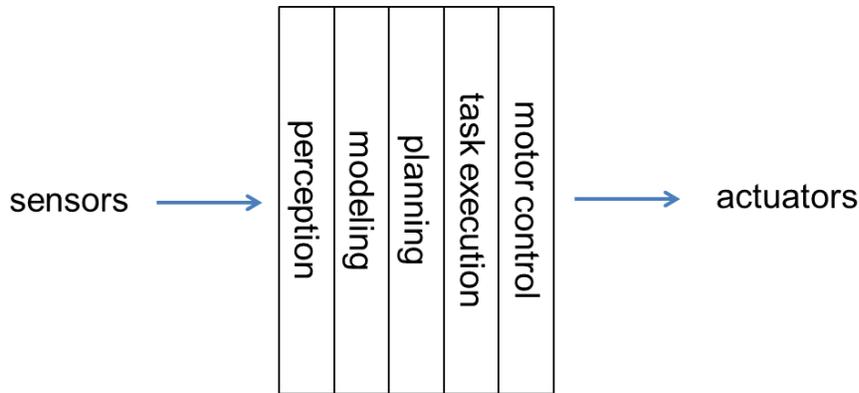


Illustration I9 (Vertical stratification: perception – internal operations – motor actions)

Following this train of thought, i.e., placing emphasis on large, elaborate and specialized strata, one has to construct:

- a) A detailed “world model”, integrating and augmenting sensory input
- b) Some representation of the body, being an element of the world-model
- c) An impressive set of “thinking rules”, including many heuristics
- d) A bunch of (flexible) behavioral strategies and tactics,
- e) Meta-rules, enabling the system to change the way information is processed, and possibly the whole setup, if necessary.

Therefore, perfecting this kind of “brute force attack” straightforwardly leads to complex “world models”, impressive sets of cognitive rules, and sophisticated action patterns, all of them increasing the computational burden, and slowing down reaction time considerably. In the end, this is one of the main reasons why classical AI failed: Although exquisite hardware is able to sustain a very elaborate software system, volatility and complexity of real world situations overpowered computational forces. Given this, Brooks’ (1999: 5) ingenious idea was to turn the ‘cognitive landscape’ upside down:

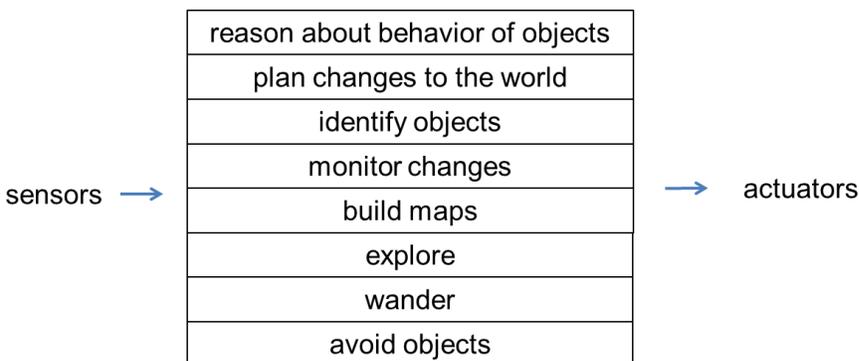


Illustration I10 (Horizontal tiers: Information processing on several levels)

Robots using his paradigm succeed in more complex environments than their predecessors and could react in due (i.e., real) time. Note the general advantages of this kind of stacked architecture:

- Given some input, there can always be a behavioral *answer*; i.e., fast responses – reflexes - at the bottom; “emotions”, encoding imprecise heuristics and vague strategies in-between; and “cognitive” responses, taking into account a lot of information in a rather explicit way, towards the top. At the very least, such a system does not stall when matters are urgent, and may find more suitable responses if time permits.
- It is *hierarchical*, with complexity increasing from bottom to top. Thus, rather primitive or standard behavior can be delegated to lower-level automatism, yet higher modules, much more complex but drawing on the pre-processing of the lower tiers, may intervene when appropriate.

It seems to be no coincidence that this kind of elegant and flexible organization can indeed be found throughout artificial and natural dynamic systems. Multi-layered architectures have become the most important IT environments (in particular the n-tier application architecture, and the ISO/OSI model of information interchange). It is also well known that the nervous system is organized in a similar way (Alexander et al. 1986, MacLean 1990, Freeman 1999, Haykin 2013, p. 39) which corresponds nicely to a multitude of hierarchical conceptions in psychology (Freud’s psychodynamics, Maslow’s hierarchy of needs, Kohlberg’s moral tiers, Jensen’s theory of intelligence, and Loevinger’s ego development, to name but a few).

Step 4: Modularity

Both natural and contemporary technical systems are built of modules, i.e., functional units, serving some purpose. For example, the hippocampus plays a major role in memory building and retrieval, the amygdala deals with emotions, and vast parts of the occipital lobe process sensory input. In general, “it is a basic principle of neuroscience that the cerebral cortex is divided into segregated areas with distinct neuronal populations...This *anatomical* classification of neural areas can serve as a basis for classifying cortical regions according to their function” (Bermúdez, 2014, p. 248, emphasis in the original).

Let us now describe how such modules (Fodor 1983, Szentágothai 1985, p. 6) work together and can be combined into an overall hierarchical structure (see below, but also Marr (1982)).

A single module copes with a certain task and interacts with its environment. In other words, there is input, output and internal processes:

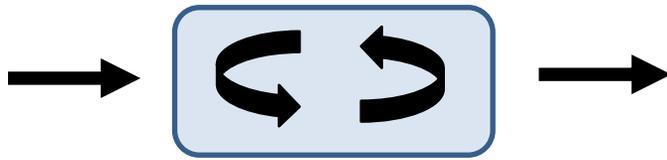


Illustration I11 (A single module, i.e., a functional unit)

Next, suppose two modules interact with one another. That is, they exchange information, each of them influencing the other to a certain extent:

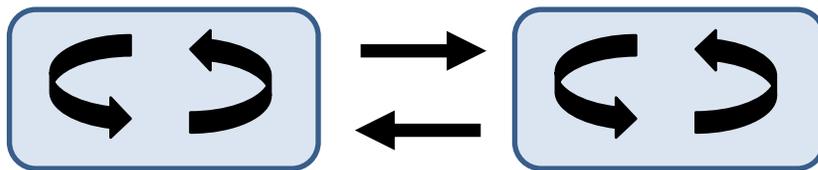


Illustration I12 (Interacting modules)

It is important to grasp that this kind of connection can be understood in many ways. Consistently, communicating modules may serve quite a number of purposes:

First, the modules are no longer independent. Rather, they are (more or less tightly) linked, having some impact on each other. If their interactions are numerous or strong, they should even be considered a compound unit. Typically however, there is differentiation (since the modules are distinct), as well as integration (since the modules are correlated).

Second, the modules exchange information. If the modules process similar kinds of information, e.g. about the same phenomenon (as in the case of sensor cells), it makes the process more reliable. (Redundancy allows for error detection and deletion.) If the modules process different kinds of information, a more complete, synthesized picture becomes possible. In any case, the proverbial truth is that there is strength in union (co-operation).

Third, suppose the module on the left hand side influences the module on the right more than vice versa. This results in a net influence of the former module on the latter, indicated by the red arrow (vector) in the next illustration:

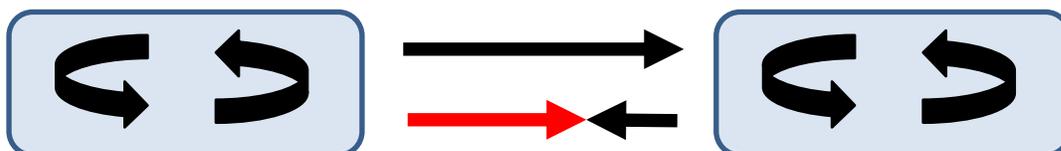


Illustration I13 (Modules' mutual influences and net impact)

In other words, since the rightwards flow of information is more important (e.g., larger) than in the other direction, the left module “has more to say”, and the processes within it are more important than the processes within the module on the right hand side. Thus it makes sense to arrange the modules in a hierarchical manner: In the next illustration (I14), the strength of the arrows indicates their importance, in particular their impact on other parts of the system. Note, that the output of the upper layer is defined (mostly) by the state or, more generally, by the inner processes of that layer - and not by the input it receives from the lower tier. This means that the locus of control is rather “upstairs” than “downstairs”: In other words, a hierarchy always goes with a control structure. In the extreme, the upper layer determines what is happening on the subordinate layer, there is a master and a servant module, with the first dominating the second.

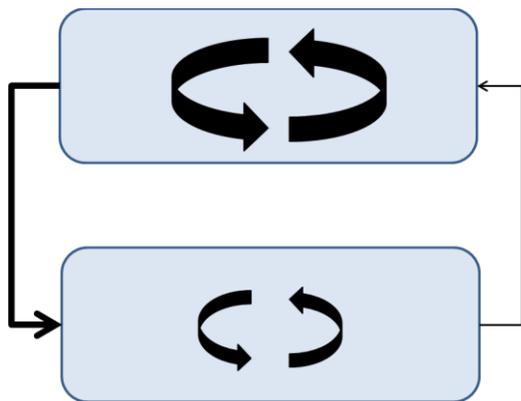


Illustration I14 (The same recursive structure, emphasizing impact)

Fourth, the two modules plus their connections form a recursive system. The arrows combined constitute a feedback loop, thus creating a system with its own internal dynamics. If the two modules influence each other in a nonlinear way, which should be the standard case, several stable regimes may evolve, but also chaotic behaviour is possible. Quite typically, however, a single equilibrium should be dominant, caused by a rather stable “division of power” between the modules. Since this state is reached spontaneously, one could call such a kind of behaviour “self-organized stability”. For an early adoption of this idea see Miller et al. (1960).

Fifth, depending on the strength and the impact of the various connections (and thus loops), modules may be just loosely connected, associated or strongly linked. They may occasionally exchange information, communicate on a regular basis, or work together as an integrated functional unit. Large parts of the cortex deal with association and deliberation; features that are supported by volatile netlike structures. However, in the sensor and the motor arena, there are rather treelike structures, collecting, analysing, and finally fusing information, or acting as directed command chains. In general, “form follows function”.

Putting everything together, one obtains a dynamical, hierarchical system. On each of the tiers, modules and larger functional units are working together on an equal footing. However, between the tiers, it is different (see illustration I15).

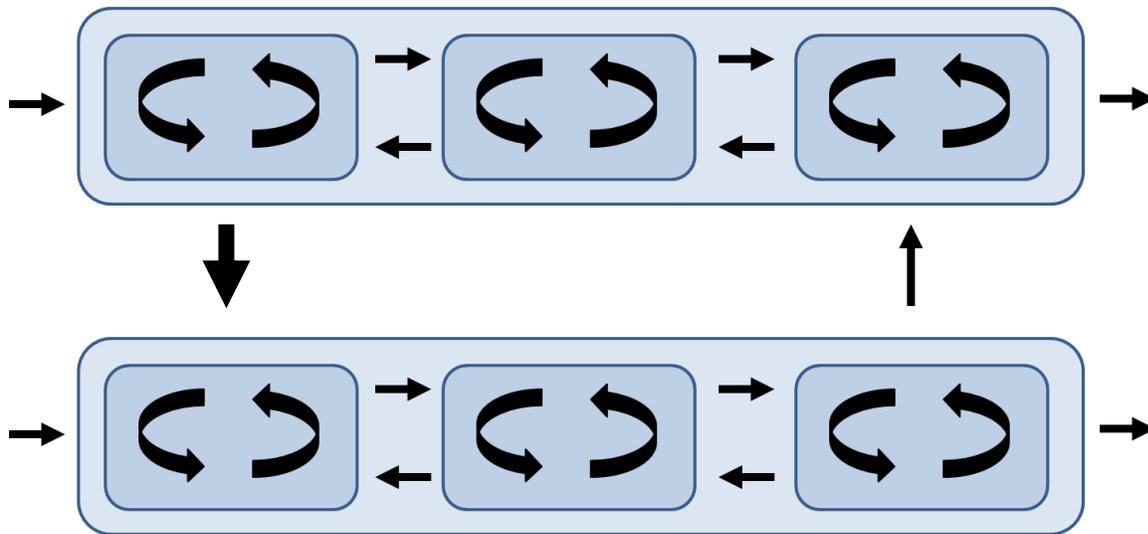


Illustration I15 (A multi-tiered system)

This overall conception envisages the brain as a dynamic system, composed of various hierarchies and many modules. It is held together by innumerable loops serving various purposes, in particular feedback, integration, transmission and control. Given this basic organizational structure, the whole system is stable, flexible and adaptive (no contradiction), and complex behaviour is the rule rather than the exception.

Note, finally, that the development just described is mostly self-organized. That is, depending on the dynamics within and between the modules, but also with the outside world, larger functional units and layers may evolve quite spontaneously. We will elaborate these ideas in the next section.

Step 5: Neural Networks

Biologically speaking, it is well-known that neural networks are the basic building blocks – modules - of the brain (e.g. Szentágothai 1985). However, also from a technical perspective, they seem to be the “right stuff”:

1. They are dynamical, adaptive and self-organizing systems (Kohonen 2001).
2. They are computationally powerful, in the sense that any mathematical function f can be calculated with the help of an appropriate neural net. Given input x , the neuronal network will produce $y=f(x)$.
3. Information can be stored (and retrieved) efficiently and robustly in the wiring between the neurons (Rosenblatt 1958).
4. “What fires together wires together”, i.e., there is a simple and general learning rule (Hebb 1949): The association between neurons is strengthened when they are commonly active
5. Neuronal networks are stable, but there is also a certain amount of plasticity. Thus they can change (learn) while on duty.

The history of artificial neuronal networks is inseparably linked with AI and Marvin Minsky’s (1927-2016) enormous influence. On the one hand, this researcher founded classical AI in the 1950s. On the other hand, he pointed out major computational weaknesses of early neural networks (Minsky and Papert 1969). Thus, for decades, classical AI became a paradigm, and neural networks were rather neglected. Even today, despite the biological start and motivation, and although almost every publication on neural networks refers to information processing in the brain, research focusses on formal aspects. Thus, neural networks are mainly used as a particular tool in mathematical optimization and statistical learning (Du and Swamy 2014).

It is somewhat astonishing and shows the immense potential of neural networks that they do well in arenas far away from the challenges where they originally succeeded. Therefore, mainstream research would fare better if it focused on the tasks of real-life (cf. some chapters, in particular the last one, in Haykin 2013). These are many-faceted, often vague and error-prone, very dynamic, involve sensory and motoric tasks, and have to be solved in real time. Cirešan et al. (2012) give an example: “The human visual system efficiently recognizes and localizes objects within cluttered scenes... Deep hierarchical neural models roughly mimic the nature of mammalian visual cortex, and are among the most promising architectures for such tasks.”

Carrying the analogy further, in the natural and in the technical world, the basic building blocks are quite simple and similar (circuits), and can be readily assembled into more complex functional units. Operating systems keep the body alive and on track (homeostasis, homeokinesis), languages directed towards problem solving are important, and, despite enormous complexity, common architectural principles keep chaos at bay. Finally, it almost goes without saying that software has to be supported by adequate hardware. Since psychology builds on physiology and anatomy, our species should and indeed does possess the highest encephalization quotient.

Step 6: Development and learning

Not surprisingly, for their mental abilities to develop and flourish, animals with large brains need much time, and even adult teachers to guide them. *Homo sapiens* has reached the far end of this evolution: Our children require several decades of education to finally reach cognitive and personal maturity. Why? First, there is a simple physical reason: Much of the available energy is consumed by our nervous system. Thus, when the brains of children are developing fastest, i.e., when they are about five years old, physical growth is slowing down (Kuzawa et al. 2014), and has to be postponed until adolescence. In this sense, man is a very powerful mobile IT system whose development touches upon physical limits. Second, the long timespan seems to be due to the sheer number of abilities that have to be acquired and mental structures that have to be erected. However, third, due to the organizational principles just described, there hardly seems to be an alternative to the successive and gradual development of modules and their connections: Neural networks need to mature, and the whole system has to (be) adapt(ed) to its environment.

In other words, although we seem to be on the right track, creating a sophisticated, flexible and, at the same time, stable mental system isn't an easy task (Rubenstein and Rakic 2013). In particular, there needs to be an equilibrium between internal processes and the incorporation of (new) sensory input. Behavioural responses must be calculated in time, etc. Finally, all these organizational structures and processes, heavily dependent and building on each other, and interwoven by countless feedback loops, have to be precisely parametrized in order to avoid over- and under-stimulation. This seems to be the reason why some authors refer to the fitting image of a "finely-tuned orchestra" to describe the immense amount of precise feedback, control and timing necessary.

Instead of trying to assemble the final result all at once (AI's hopeless endeavour), the common general idea in pedagogy as well as in "developmental robotics" (Weng et al. 2001, Asada et al. 2001, Asada et al. 2009) nowadays is to create a "self-inflating" system, i.e., a system that remains stable although it is able to learn immensely (Cangelosi and Schlesinger 2015). That's quite a challenge, since altering a complex system threatens its functionality (never change a running system...); yet it is crucial to add, run in and restructure functions, modules and layers. It is a formidable task to move from primitive to elaborate and complex, from reflexes and blind imitation to critical reflection, without shutting down the system even once.

A major advantage of multi-tier architectures is the fact that they can be extended gradually: Loop by loop, module by module, and tier by tier. At the same time, most of the features already in place stay where they are. In other words, such systems are open to further development as

well as being conservative. That is, extra functionality may be added without jeopardizing the system's overall stability.

The basic point in progression is the permanent and intense interaction of the individual - and its programming - with the environment (Pfeifer and Scheier 1999). It is this ceaseless, and at the same time rather selective, interaction between the individual and its environment that pushes development forward. Focusing on either nature or nurture, or trying to separate their impact, seems to wander off course or even miss the target. In other words: Because of situatedness, the question as to how much is inherited or due to the environment is rather misleading. Talent may be important, but without appropriate training, it will never flourish; we need to understand the interaction of the organism with its environment in order to achieve optimum results.

In this vein, Kurt Lewin (1939) proposed "field theory", that is, he located the individual within its so-called "life-space", i.e., a complex environment endowed with social "force fields" of all kinds. Within these boundary conditions an agent acts and develops. Quite similarly, Der and Martius (2011), p. XI, write: "...behavior generation in complex robotic objects is improved and stabilized by taking brain, body, and environment as a whole. The playful unfolding of behavioral patterns offers a new way of getting the embodiment of the agent involved."

Since learning is "online", curiosity - resulting in the (systematic) exploration of one's environment - is crucial. Conceiving "a roadmap for cognitive development in humanoid robots" (Vernon 2010), researchers in the field do not try to teach their robots particular tricks for a restricted environment. Rather, their emphasis is on curious "playful machines" (Der and Martius 2011) actively exploring their environments. Given intrinsic motivation (drive), a robot moves around, gathers experiences, constantly learns and develops step by step along its own path.

Although sitting idle (the so-called "lazy robot effect") is less dangerous than active behaviour which may at times even kill the proverbial "cat" - at the end of the day, intrinsically motivated robots have learned more about their environment, and are thus more successful than sluggish ones (cf. Der and Martius 2011, Cangelosi and Schlesinger 2015, in particular Chap. 3). In a word, it pays to explore and thus take in the world one is inhabiting.

The general developmental direction is bottom up: from primitive to complex, and from implicit to explicit. Thus, in order to understand and develop such a system, it seems to be a good idea to start from scratch, i.e., with the very first layer, with simple responses, and rather primitive tasks. Straightforward observations confirm that babies, but also successfully developing robots, begin with the basics (e.g., gazing, grasping, sitting), and spend much time acquiring fundamental skills. Probing their environments, they move from the primitive and even rudimentary to the sophisticated and complex.

For example, first a child learns to lift its chin and its chest. Then, it is able to sit. Subsequently it crawls, stands, and finally walks. Most of these abilities have to be practiced many times, and are first accomplished with and then without the help of others. Piaget (1952) conjectures that “schemata” are among the basic building blocks of human knowledge. A schema is a unit of knowledge, i.e., it is like a file, containing syntactic, semantic or pragmatic information. Moreover, there is a simple mechanism which could be called the “assimilation-accommodation loop”, extending and sophisticating schemas:

1. Internally, one starts out with some rather primitive schema, on the most basic level it is an inbred capacity (e.g., the ability to grab or to make noise)
2. *Assimilation* refers to the process of fitting new information into pre-existing cognitive schemas. That is, some new experience is processed with the help of the existent framework, adding a new chunk of information to the latter, but not altering the received schemas.
3. However, at times, it may be necessary to change existing cognitive schemas. This process is called *accommodation*, and happens when the existing set of schemas does not work with a new object or situation. In particular, a crude schema (idea, concept) may thus become more differentiated.
4. With every loop of this kind, the (internal) cognitive system becomes more complex. Thus the agent is able to deal with more objects and situations, or to treat a particular problem in an increasingly sophisticated manner.

The same author’s “developmental stage theory” describes in some detail how children evolve cognitively. Altogether, he finds four qualitatively-different levels, and a more basic level has to be “completed” in order to move on.

Small children (up to 2 years) start in the “sensorimotor stage” when they first gain experiences with their sense organs, their movements, and the co-ordination of the two areas. In other words, babies and toddlers develop basic sensory and motoric abilities, and learn to close the sensorimotor loop (e.g., object perception, face recognition, gaze following, selective attention, manipulation, and locomotion).

At the age of 2-7 years, in the “pre-operational stage”, children are egocentric in the sense that they know about their own position in the world. However, it takes (them) a long time to transcend this particular perspective. Attention is also restricted to a single feature of a situation.

Between 7 and 12 years, children reach the “concrete operational stage”. That is, the number of mental objects considered at a certain moment grows, they become able to simultaneously grasp

various aspects of a problem, i.e., they get an overview, and may thus solve increasingly complex problems in concrete situations.

At the age of 12 to 15, the abstract, level, the “formal operational stage” is reached. Juveniles learn to work with arbitrary assumptions (“what if...”), and are able to check the consequences of hypotheses systematically. Deductive and inductive reasoning become possible. Finally, they may leave familiar realms, and consider instead general and abstract problems, quite removed from their daily experience.

Since a lot of energy and effort have to be spent in order to get a fully-functional result, rather typically, mental “growth” is tedious, with new features emerging gradually. Noticing that learning by imitation is easier than learning by reflection which, in turn, is less dangerous than learning by bitter experience (cf. Confucius), it is no surprise that copying successful strategies applied by others, e.g., imitating what they do, is the most common form of making progress. Thus we are constantly checking the activities of others, their mental life included (thus creating a “theory of mind”, i.e., we are able to detect and understand the expressions, intentions, and beliefs of others). Even on the hardware layer, we are equipped with so-called mirror neurons that have specialized in detecting interesting behaviour in others. Recently, robotics has begun to implement these devices and ideas in machines (cf. Cheng 2015, Chapter III).

More generally speaking, prior information built right into the design of the system helps a lot. Haykin (2009), pp. 58-59, gives a number of reasons why: A specialized neural network is smaller than its fully-connected counterpart, needs smaller data sets for training, learns faster, and the network throughput (information) is accelerated. In the most extreme case, an incarnated structure or feature need not be learned at all, and since such a built-in structure can be applied without delay, it can also be expected that nature applies this trick whenever possible.

In sum, prior structure (instinct, talent, “readiness” for some development, etc.) is basic, imitation and repetition help a lot, and personal experiences, including typical mistakes, are inevitable (you cannot ride if you have never fallen off your horse). In addition, much learning is explicit, and as a consequence, thinking and understanding (at least in humans) should not be underestimated. Learning by reflection may be noblest, but much more importantly, one has to think by oneself in order to become smart. To grow strong, the brain (like muscles), needs permanent, well-targeted training. As we all know from the education of children, this kind of learning can be accelerated by suitable hints, specific rewards and (at times) punishments from a more experienced person, i.e., a teacher (e.g. Vygotsky (1978)).

So “guided self-organization” (Der and Martius 2011, Chaps. 12-14) seems to be the most promising method of development. Along this way, children detect and cultivate internal processes such as attention, motivation, estimating and weighting, helping them a lot in acquiring

explicit knowledge about the world they live in. With knowledge comes reasoning (Mareschal et al. 2009), but also deeper insight and evaluation. Finally, having understood many explicit features of the natural and the social worlds, and having matured on the inside, they have/are grown up, able to deal with challenges of all kinds in a sophisticated way – their way. “Coming of age” means to receive full authority of one’s own life and to be in charge of further self-development.

A progressive mental system depends on major feedback loops connecting it with its environment, but also internal circuits grounding it in more basic units, including the physical body. Its growth is not random, but well-structured: Auto-didactically, but also assisted by teachers, a multitude of modules dealing with particular tasks are developed sequentially. In order to become fully functional, they have to be linked and integrated into a large network, finally leading to comprehensive mental layers that rest on each other. The following table summarizes our mental edifice:

Mental Layer	Processes	Building blocks	Main location	Evolutionary stage
Apex	Structured reasoning, language	Concepts	Associative areas of the cerebrum	Homo sapiens
Top	Cognitive	Cognitions of any kind, in particular, images	Cerebrum	Primates, some whales and birds
Intermediate	Emotional	Emotions, e.g., fear	Limbic system	Mammals
Basic	Reflexes	Drives, rigid procedures	Brain stem	Reptiles
Elementary	Fundamental Responses, often 0-1	Communication pathways between neurons	Neurons, and sets of neurons	Animals with nervous systems

Table T1 (Mental organization of biological species / natural systems)

Step 7: Towards consciousness

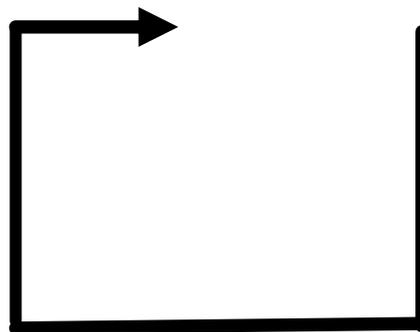
Given a rather complex and multi-layered system, it remains to explain how self-awareness fits into this picture. In more detail: How does such a system beget an idea of its own existence?

First, it is crucial that the individual is a part of the whole situation. In particular, its mental equipment is a decisive part of the information flows running within the body but also between the subject and its environment. In other words, the layers of the “central processing unit” communicate with one another, and, on each level, there are strong feedback loops between each layer and the environment.

Second, since the individual is a part of the whole system, there exists a token for the individual on every level. Depending on the tier, this token is an emotion, an image (or a more complete sensory impression, including, for example, a voice) or a concept (i.e., a word for oneself). Since the individual being is crucial and since it is located in the centre of action and perception, these tokens – placeholders - are out on a limb.

Third, combining the properties just described, it is straightforward to conclude that the individual “notices” itself in the sense that the various tokens detect themselves due to tight circularity. A certain token, being a representation of oneself (or one’s self, respectively) on a certain layer, looks ahead and therefore perceives the back of itself.

A famous picture by Matisse exemplifies this situation perfectly:



Picture P1 (Matisse 1937: “Not to be reproduced” and corresponding epistemic structure)

This organization of the mind seems to fit quite well to our impression that higher developed animals have some insight into what is going on. They are not just automata, following pre-adjusted instincts. Rather, they are flexible, able to adapt to new challenges and environmental conditions and, in the sense just described, seem to have an idea of themselves. In other words, due to self-representation(s), they are able to distinguish (to a certain extent, more or less precisely) between themselves and the rest of the world.

Now it should come as no surprise, that the most elaborate theory of self-awareness, developed by Damasio (1995, 1999, 2010), is a hierarchical three-layered theory of consciousness. For a closely related account see Donald (2002).

1. First, there is the protoself. All sensory inputs are integrated in one basic brain structure: the hippocampus. Its first task is to keep the system alive, i.e., to guarantee homeostasis.
2. Second, in higher developed animals, feelings emerge. An emotion is an unconscious reaction to any internal or external stimulus which activates neural patterns in the brain. A ‘feeling’ emerges as a still unconscious state which simply senses the changes affecting the protoself due to the emotional state. Core consciousness is the feeling of knowing a feeling. (Note the reference of an emotion to other emotions. Thus a second layer emerges: feelings based on other feelings.)
3. This is also where Damasio puts his third layer of self-reflectiveness, which he calls “extended consciousness”. Although he thinks that language is not essential in its constitution, he emphasises the role of memory in order to build a particular personal perspective, including ownership of thoughts and the power to manipulate mental items. Thus, we understand in a much more explicit way than before who we are (i.e., our properties), our position in space (in nature and society), and the arrow of time. In particular, there is a stable personality with an autobiography.

Although the author of this contribution agrees with most of Damasio’s conception, I think that language is crucial. The main reason being that due to circularity and thus self-reference, it is rather straightforward to perceive one’s flipside. However, a really strong “mirror” (indicated by the red line in the following illustration, also see steps 8 and 9 in section 1) is needed to look oneself straight in the eye. Schematically, one obtains the following development:

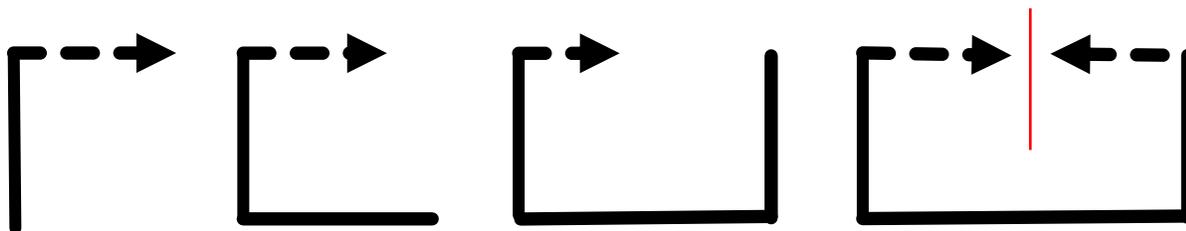


Illustration I16 (Body (solid lines) and perception (dashed arrows)). From left to right: Unaware – Noticing oneself [less/more] – Fully self-aware). Details in text.

Newborn children are hardly aware of themselves (Rochat 2003). The decisive steps occur later and can thus be observed: When small children label all the objects in their vicinity, they also use a name for their own body. Yet they need not understand that this concept is special. However,

when the world model and their language proficiency improve, they have two efficient ways to describe matters (helped, of course, by the more basic layers and their environment).

In both, the sensory and the verbal realms, the representative of the body is a well-defined, crucial entity: its image and its name are located at the centre of operations; all sensations, actions, and mental processes revolve around these tokens. Ordinarily, the formation of a concept is like the development of a dictionary – one simply learns which word has to be used for a certain sensory input. But since the program is continuously observing the body in which it is located, no distance is possible. Moreover, combining the particular body image with the corresponding, equally remarkable, word yields a truly exceptional concept; a concept representing “the centre of the world” (more precisely, the world as seen from my point of view).

Upon changing perspective, typically the name of an object remains fixed (an apple is an apple, no matter who is talking about it). However, when others talk about themselves, they also always use the same word – “I”, and a number of different words for others. Adopting this practice distinguishes “me” from all the other objects and phenomena around. (In other words: observing others, how they act and how they perceive themselves may serve as a “role model” or as a catalyst in detecting one’s own self or quite simply “oneself”.)

Thus “I” is not really “my” name, but rather a particular point of view that should be distinguished from others, be they objects or persons. Being inseparably connected with private feelings, observations and actions, it stands for my (complete) subjectivity. This and only this concept represents myself. Full self-awareness means possessing such an extraordinary concept and understanding its entire meaning: First, “I” stands for my humble self, and not anybody else(s). Second, my self is not void but inseparably linked with exclusive, body-related information. Third, “I” is / am defined by a distinct, stable line separating myself from the rest of the world. Altogether, self has come to mind.

Our line or argument and common knowledge may be summarized in the following table:

Mental Layer	Crucial Processes	Mental token for oneself (Representation)	Personal insight
Apex	Language	Precise concept: I, combined with a stable division between one’s self and anything else	Full personal awareness and situatedness
Top	Cognitive	A complete “image” of the body’s current state	Extended consciousness
Intermediate	Emotional	The feeling of what happens: Integrated multisensory maps	Core consciousness
Basic	Reflexes and drives	Taking notice of one’s existence	Protoself

Elementary	Fundamental responses	Almost non-existent	None
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Table T2 (Levels of consciousness reached by biological species)

Reading the last table horizontally reveals that the multi-layered architecture yields qualitatively different descriptions of the world. Therefore, due to situatedness (embodiment) and thus circularity, different representations of oneself emerge. Depending on the level, a more or less clear understanding of one's self is reached, i.e., a certain kind of self-awareness follows suit.

Reading the last table vertically shows several tiers, resting on one another. Evolutionary speaking, each new layer is associated with a characteristic kind of process, language being the last and thus uppermost. The descriptions of oneself available (one "self" on each level) become more and more explicit and precise. They build on each other, until finally, conceptually clear, stable and comprehensive personal awareness is reached.

Note that the whole edifice as well as personal awareness is differentiated and integrated. On the one hand it makes sense to distinguish several kinds of consciousness - on the other, they are not just tightly linked, but coalesced into a single mental unit. We will elaborate on this important point in the next section.

(Continued on Part III)

Article

Roads to Consciousness: Crucial Steps in Mental Development (Part III)

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Abstract

This contribution explains several “roads to self-awareness”, all of them based on the natural sciences. The first one follows our bio-psychological evolution. The second road starts with the engineer’s point of view and mainly builds on information science and technology, in particular robotics. The third road taken is the most abstract - It exploits complex dynamic systems and their emergent properties. Despite their different origins and methods, these lines of investigation converge. That is, the findings of various fields can be combined into a unified theory of mind and self-awareness, which is the main purpose of this paper. This overall synthesis suggests that the mind results from a multi-hierarchical organizational structure, and self-reflexive flows of information in embodied systems. In addition to this, stable self-awareness appears spontaneously in sufficiently complex robots, when the system’s capability of describing itself crosses the level of conceptually clear information processing (thinking). As an application, one obtains a number of construction principles for mentally developing systems that are explained towards the end of this contribution.

Part III of this four-part Article includes: 3. Complex Dynamical Systems.

Keywords: Self-consciousness, self-awareness, free will, dynamic systems, hierarchical systems, language.

3. Complex Dynamical Systems

More is different (Anderson 1972)

There is yet another, more principled and abstract, line of argument leading to consciousness. Apart from putting this remarkable phenomenon in a larger perspective, it gives some concrete ideas about how it develops and how it is structured. Applying these insights may help to program “artificial intelligence”.

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A) Emergence of new properties

For a long time, reductionism ruled. That is, in order to understand some phenomenon, it is crucial to break the phenomenon down into its constituents and analyse their causal relations. Having thus grasped the inner workings of a mechanism and its main elements, one should at least be able to predict its major results. In a sense, this is the overall “modus operandi” of science: analyse an interesting phenomenon in detail, until you have understood what is going on.

However, “the ability to reduce everything to simple fundamental laws does not imply the ability to start from those laws and reconstruct the universe. In fact, the more the elementary particle physicists tell us about the nature of fundamental laws, the less relevance they seem to have to the very real problems of the rest of science, much less to those of society. The constructivist hypothesis breaks down when confronted with the twin difficulties of scale and complexity” (Anderson 1972, p. 393). In other words: having understood the details typically does not imply the big picture. Why not?

The reason is that “at each level of complexity entirely new properties appear, and the understanding of the new behaviors requires research which I think is as fundamental in its nature as any other... each level can require a whole new conceptual structure. Psychology is not applied biology, nor is biology applied chemistry... the whole becomes not only more than but very different from the sum of its parts” (Anderson 1972, pp. 393-396).

In the last twenty years or so, the associated philosophical position of *emergentism* has gained ground (for a short introduction and a long list of references see de Souza Vieira and El-Hani, 2008), opposing reductionism, and stressing the importance of organization and supervenience. A particularly interesting account of emergent phenomena is given by Deacon (2007). The most important ideas, however, originated in the natural sciences. For an overview see Èrdi (2008) but also Murphy et al. (2007).

Given this viewpoint, one should not expect that self-awareness may be explained by way of reducing it to some fundamental physical law, like Heisenberg’s uncertainty principle, or some anatomical detail, like microtubuli (Hameroff and Penrose 2014). On the one hand most scientists would agree that the brain can be reduced to standard physical particles and forces, and that neurons are the basic elements to be considered. (There is no particular mental “stuff”, or “vis vitalis”, etc.). However, on the other hand, there is also a consensus that the brain’s organization - its anatomy and physiology, i.e., its structure and dynamics - is crucial. That is, despite material reduction, it is a very persuasive idea that self-awareness is an emergent

property on a certain level of (biological) evolution, more precisely, of a certain kind of (complex) organization.

One of the main theses of this contribution is the claim that the systematic use of a rich, natural language leads to completely new features, in particular self-awareness. More specifically, the above arguments suggest that our personal self is the consequence of conceptually-clear, circular information processing, enclosing a preeminent mental token for the person processing the information. In a nutshell, the phenomenon of self-awareness is a major consequence of a sophisticated mental organization, i.e., the multi-hierarchical and self-reflexive flow of information in situated robots, based on precise chunks of information about the agent and its environment.

B) Building the final layer

The crucial problem for nature and thus also for engineers and computer scientists consists in constructing a stable hierarchical structure, governing the dynamic flow of information (within the robot, but also in relation to the world outside). Piaget's idea of assimilation and accommodation describes an elementary mechanism, extending the mental system. However, it does not explain how new modules or even layers are created, developed and integrated.

Since we claim that language is crucial for self-consciousness, let us try to explain in some detail how the crucial new feature of language was added, i.e., how the language sub-system may have developed, and how this innovation led to the unique human mind. (Similarly, for every more basic tier, one may describe how the next layer was possibly built on top of the existing structure.)

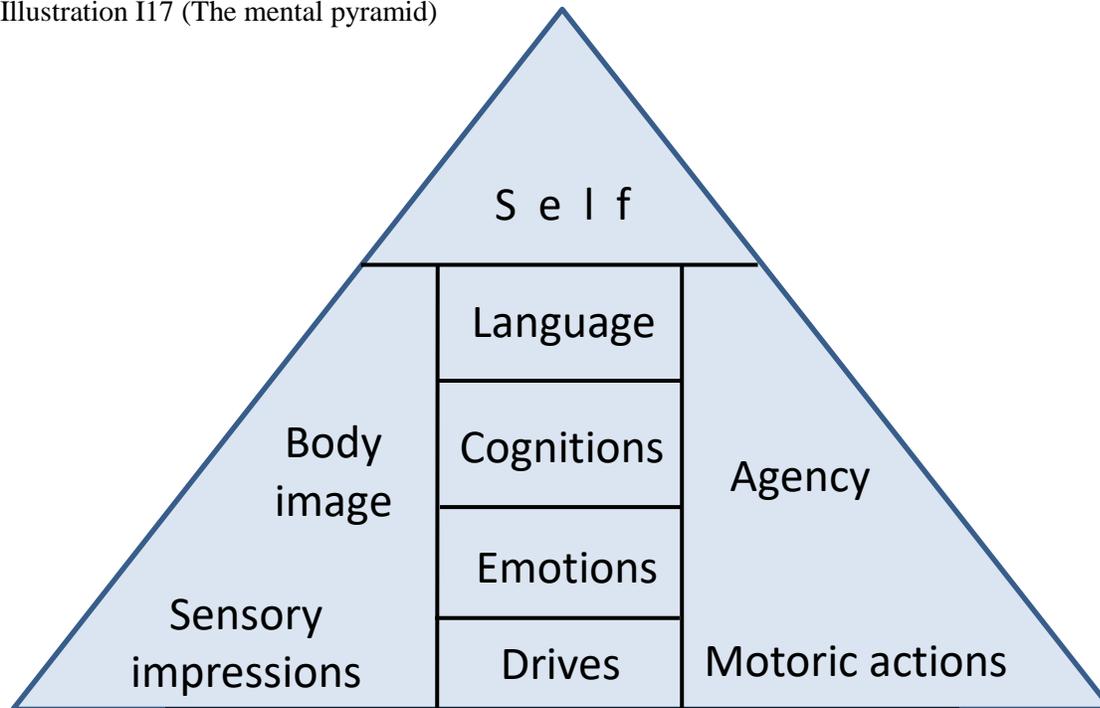
- a. **Reaching the realm of language.** Great apes possess a sophisticated visual image of the world. Of course they are able to hear and to listen, and can produce a broad range of sounds. Linking a specific sound to a particular sensory impression creates a primitive concept. First, perhaps, accidentally, but, if sounds with a particular meaning, words and concepts bring about an evolutionary advantage, it pays to repeat the process of concept-formation. Thus, next to the familiar sensory model of the world they inhabit, a new module begins to develop.
- b. **Establishing and consolidating the new function.** Dozens, hundreds, and finally thousands of concepts define a vocabulary which is enriched by every new concept created. Combining these words according to rather constant rules produces an even more powerful way to describe persons, phenomena, and habitat. Thus, with the inner processes of the new module in place, this module consolidates. On the one hand it is thoroughly grounded in bodily experiences (sensory perceptions of all kinds, but also motor actions), on the other hand, it has rules of its own (a grammar). Playing around with concepts and grammar finally creates

the mature functional system of language, i.e., a versatile tool with a complex structure and a “life of its own”, able to describe and explain what is going on.

- c. **Feedback.** The new functional system, developed alongside the sensor layer, has a major backlash on the received organisation. That is, language and its structure influence sensory impressions or more general cognitions, i.e., the way, we “see” the world. At the very least, concepts provide a second “view”, they add precision, and grammatical structures enable arguments and discussions.
- d. **The impact of language.** Given the situation of illustration I12 (two interacting functional systems) we moved straightforwardly to illustration I13. In other words, since we are dealing with a recurrent system, we should look for its dynamic equilibrium, i.e., the amount of control exerted. Numerous authors (e.g., Sellars 1970, Campbell 1974, van Gulick 1995, Deacon 1997 & 2007, Murphy et al. 2007) have considered this question. In general, the feedback of a new emergent feature on the elements on which it is founded is called a 2nd order constraint. Such constraints can be very powerful, therefore Haken (2006) uses the term “enslavement,” Bunge (2003) speaks of “submergence”, and Sperry (1973) coined the term “overpowering”. However, with respect to mental processes the most frequently-used term nowadays seems to be “downward determination” or “top-down causation” (or a combination of these words).
- e. **Mental reorganization.** All these ideas have in common that they indicate a tremendous influence of language. In effect, with the feedback loops in place, the impact of language leads to a “landslide”, altering the mental landscape dramatically. Since we described it in much detail in section 1, a succinct summary should suffice here: First, owing to circularity, there is a particular token standing for one’s self on every tier (see Table T2). Second, in particular, there is a word for myself on the top layer, and an elevated image of my body in the visual domain. Third, due to the tight feedback loop between these layers, they act as “internal mirrors”. Fourth, the self-concept and the self-image may combine, forming a stable and well-defined (personal) identity that is enriched by contributions of more basic layers (e.g., the protoself). Fifth, drawing a razor-sharp line between ourselves and the rest of the world, we become aware of our precise position in space and time.

Altogether, the edifice looks like a pyramid, governed by a personal self:

Illustration I17 (The mental pyramid)



The *new organization* that has thus evolved features a personal self, i.e., a clear sense of self-awareness, a definite idea of oneself, on top of the restructured mental edifice. This self is rooted in and based on several layers with their particular components (e.g., concepts) and internal structures (e.g., grammar). On the one hand - bottom up - the self incorporates facets of each of the more basic layers (in particular, it has a cognitive and emotional flavour), on the other hand it is an agent, controlling - top down - parts of them. For example, it is able to act (voluntary motor function), talk (conscious command of language), think (intentional use of cognitions), and direct its sensory alignment (focused attention).

However, each layer also has a “life of its own,” and the farther away it is from the top, the more so. Owing to the organizational structure, we are able to cope with language best; words are right “on the tips of our tongues”, ready-to-use. It is more difficult to control memory and general cognitions: We may not be able to retrieve a certain memory, rotating an object with the inner eye is tedious, and it is very difficult *not* to think of a pink elephant if told so. The motoric realm is divided into voluntary and non-voluntary motor functions. Since we have no direct access to the emotional tier, we are also not able to control emotions directly. If a person is sad, it does not really help to be told to cheer up, and, if frozen in shock, it takes a great deal of voluntary effort to overcome paralysis.

It may be added that quite obviously, the faculty of language, combined with a sense of self, also greatly facilitates and improves communication with others. Thinking in tiers, straightforwardly, a social tier may be added on top of the above pyramid. In other words, thanks to language, the

link between several individuals of the same species is strengthened and more durable social structures than ever before can be built. Thus man became the most eusocial animal ever. With the groups growing in numbers and stabilizing, this layer brought about sedentariness, systematic farming, division of labour, and a multitude of other historical traditions; in the end producing large societies, sophisticated culture and civilization.

Historically, one may distinguish three major shifts: At least 100,000 years ago, spoken language singled out the species of homo sapiens: At about that time proper burials started, a ritual that only makes sense if you have a clear idea about who and where you are (Lieberman 1991). Thousands of years ago, writing greatly increased the ability to store and pass on information, making advanced civilisations possible. The archaeological records for this development are monuments (like pyramids or defensive walls) that could only be erected on the foundations of a sophisticated social organisation. Hundreds of years ago, the formal and quantitative language of mathematics brought about science and technology, i.e., a much deeper understanding and command of all kinds of phenomena, which characterizes the modern era. Thus, taken with a pinch of salt, language-based innovations (printing and the internet included) have exponentiated our ability to learn about nature and ourselves. We truly have become the symbolic species (Deacon 1997), ruling the world.

C) The locus of control¹

The theory developed above, in particular the last illustration, corresponds nicely to our self-evident “naïve” personal everyday experience. It fits the modern idea of an autonomous agent, but also with the time-honoured view of “free will” (liber arbitrium as it has been called at least since the Middle Ages) that may be traced back as far as Aristotle’s “De anima” and Plato’s dialogue “Phaedrus” where they depicted the “I” as the charioteer of the soul. Contemporary psychologist Roth (2003) characterizes this idea by saying that the self is in superior command of thinking, planning and action, being a central decision and executive system in the mental realm. He also highlights self-monitoring, self-government and autonomy.

Although the concept of personal freedom has an air of arbitrariness and non-determinism, in particular in the philosophical debate (Kane 2011), it is mostly used in the above sense by natural scientists (Baumeister 2010). So the main connotation of freedom is the self being in charge, having a meaningful choice, being the owner of the mental edifice and the captain of the body. The contemporary challenge to the received top-down conception is bottom-up determinism. The more we have learned about the brain, the more it has become obvious that physical processes

¹ Note that throughout this article, “locus of control” is used in the sense of “who is being in charge”, i.e., an entity, that rather issues commands than having to obey them. This is quite different to psychology’s use of the term (Rotter 1966).

are the basis of the mental: All thought and emotion, perception and action, memory and personality, depend on anatomical structures and physiological mechanisms. For example, an extraordinary memory (fast, large and reliable) is needed to support language, with the hippocampus (Marr 1971) as well as the classic speech areas of Brocca and Wernicke playing major parts in this narration. In general, brain damage readily implies mental limitations. Thus it is straightforward to conclude that psychology is an epiphenomenon of neurobiology, and the striking well-known results of Libet (1985) and others (in particular, Kornhuber and Deecke 1965) have been interpreted in this way. Given the question “do we consciously cause our actions or do they happen to us?” (Wegner 2002), many natural scientists exploring the brain “bottom up” now opt for the second view. For a thorough discussion see Baer et al. (2008).

However, considering a common computer, it is obvious that problem-oriented programs near the top level drive the physical actions. In the end, the ultimate locus of control is the user, who - via the computer’s graphical user interface - tells the software and the underlying hardware what to do. The crucial flow of information consists in commands issued “top down”.

How can we explain such a kind of “free will” in self-referential, dynamical systems that we have studied? Close to our account is the idea of a “synergetic computer” (cf. Haken 2004, Haken and Schiepek 2010) which consists of at least two layers - rather organizational than physical - ceaselessly influencing one another.

The first main idea of synergetics is that the elements that make up the bottom layer may interact in a particular way, producing an overall pattern (which, due to its regularity, can be described by a few order parameters), forming the upper layer. The paradigmatic example is light: Unlike ordinary sources of light, a laser does not emit uncorrelated light waves. Instead, it produces a highly coherent single light wave. That’s the bottom up impact, i.e., the elements’ *spontaneous self-organization* into a larger and simple structure.

The second main idea of synergetics concerns the top-down impact, i.e., the consequences of the large structure (often represented by its order parameters) on the elements in the bottom layer. In the case of the laser, the coherent light wave forces single photons to oscillate in the same way. That is, the elements are no longer “free to do what they like”. Instead, they lose many, if not most, degrees of freedom and have to comply with the overall organizational structure (therefore the term “enslavement” mentioned before).

With respect to information flows in the brain, this account captures many important aspects. It is both elegant and there is much experimental evidence in favour of it:

1. We have stressed the importance of feedback, i.e., of an account that is dynamic as well as circular. Synergetics explains how a hierarchical system endowed with a feedback loop/circular causality may emerge spontaneously via “self-organization”.
2. Looking at the lower tier, there are indeed coherent waves when areas of the brain work together (Singer 2007) which are to be expected when parts – via a common order structure – co-operate (automatic “consensus-building” in the words of Haken and Schiepek 2010). More generally, in this view the “binding problem” (how can different brain parts work together when necessary) is solved via spontaneous synchronization bottom up (e.g., Fingelkurts and Fingelkurts 2004, 2013), in particular frequency locking (Haken 2002, 2008).
3. Looking at the upper tier, there is an enormous degree of information compression, since a few order parameters suffice to describe the overall behaviour. It is well known that we do not store all details of a story or picture. Rather, we retain the most interesting, striking and characteristic features.
4. Since patterns may act as the building blocks for further layers, picturing a multi-tier system is straightforward.
5. Information processing within this system is both massively parallel (since there are many modules and feedback loops) and integrated (since the circuits are all interwoven). Moreover, in stark contrast to the classic von Neumann computer architecture, most components are active most of the time.
6. Memory building and pattern recognition use the same mechanism, i.e., the feedback loop between the layers. On the one hand, “bottom up” memory building is self-acting, and to store some pattern it suffices to retain its order parameters. On the other hand, suppose there are stored parameters and some of the pattern’s features are observed. The “top down” part of the feedback loop between the layers will then fill in the missing parts, until the dynamics have automatically restored the whole pattern (cf. Haken 2004, Section 17.1). In other words, synergetics offers an elegant, “combined” mechanism of memory building and information retrieval. Data compression and recovery are understood as a kind of feature extraction and pattern formation.
7. More generally, pattern formation is a particular kind of phase transition. Without a pattern, neural activity is incoherent, yet with a pattern it is orderly. Moving to the orderly state involves characteristic fluctuations, critical slowing down, and hysteresis that have all been observed in the motor arena (Haken 2006 (Chapter 11), Haken 2004 (Chapter 12), Haken 1996 (Part II), Haken, Kelso and Bunz 1985).

8. Different patterns are associated with distinct values of the order parameters. Here, too, typical oscillations can be observed, in particular if the sensory input supports several patterns. This effect can be demonstrated nicely with the help of flip-flop images, like Necker's cube (Haken 2004, Chapter 13). Difficult decisions seem to be similar: given a certain information basis, it may be hard to choose between several options, particularly if they are equally promising (Haken 1996, Chapter 17).
9. It is well known that layers building on each other operate on different time scales (e.g., Juarrero (2009), p. 99; Newell et al. 2009, and the references given there). As a rule, the lower the layer, the faster it works (just compare representative physical, chemical, biological and social processes). Therefore, Libet's results can be interpreted in an elegant way: The basic sensorimotor tier quickly sets a behavioural default. Bottom-up, this fixing appears in the conscious mind as a decision, although, in this case, it is just an *a posteriori* rationalization. However, operating on a slower time scale, but being truly in charge, top-level consciousness may readily overrule the lower tier's move (e.g., Donald 2002, Bandura 2008, Baumeister 2010).

Self-organization and order parameters are an elegant way to explain why top-down control is the rule and not the exception. In general, the overlying tiers act as powerful 2nd order constraints influencing the subjacent layers much more than vice versa. If the bottom tier is the sensory realm, and the upper tier the cognitive realm, this corresponds nicely to the well-known view of Kant (1781) that "freedom, in the practical sense, is the independence of the will of coercion by sensuous impulses." If the uppermost tier is the self (see illustration I17), "free will" is an appropriate subjective description for the (partial) "submergence" of the lower layers. To this end, language is an excellent tool since it provides explicit knowledge representation, concise chunks of information that may be combined in a transparent way, yielding resilient lines of argument that may lead to consistent action. It is no coincidence that clear conceptual thinking and understanding, arguing, modelling and checking ideas are so important for us.

Very often, activities are first located on the top tier and subsequently delegated further down. Learning some complex task, e.g., driving a car or playing a musical instrument, starts on the conscious level. One has to understand in great detail what kind of movement of limbs is required, when which movement is appropriate and how the arms and legs interact. Thus the proverb that all beginnings are difficult: they are slow and tedious and take enormous effort. Yet a major part of learning consists in *automatization*. Experienced drivers change gear without (conscious) thinking, and once a pianist has learned a musical piece their fingers know how to move. The saying that some faculty is "ingrained" or has become one's "second nature" captures perfectly what is going on: The skill is deeply rooted within the body, and control by the upper

layer may be restricted to a bare minimum, e.g., a trigger. It is well known that typically (at least) ten years of thorough practice - 10,000 hours of training - are needed in order to learn some demanding activity “by heart”. An engineer would say that this time is needed to replace (slow) software with (fast) hardware, i.e., on the basic level, neural networks have to be restructured and programmed in order to master some specialized task.

How strong is the loop within the uppermost layer? Roth (2003) remarks that a vast proportion of neurons in the associative cortex (up to 99%!) communicate with one another. Given this finding, some have concluded that we are constructivists, mainly revolving around ourselves, and building our own world. However, this conclusion is premature. First, in the course of evolution, those who forgot the outside world did not survive. The same result would occur if we could voluntarily influence the output of our sensory devices, i.e., perceive the world as we would like it to be. Second, the top level is thoroughly based on all the other layers below; it is not a “spirit in the sky”. Third, the lower layers’ input is still important if not decisive, if “informational updates” of the top layer are frequent (e.g., several times a second, say), and if this input influences the internal (circular) processes in the top level sufficiently. That is, in order to have a stable flow of information it would be straightforward if the circular processes in the top level reached an equilibrium without external input. However, if it is mainly the impulses of the lower level(s) that gives them direction, the final result (i.e., the top down arrow on the left hand side in Illustration I15) may depend on the input in a crucial manner. (Although Lady Macbeth is just whispering - not shouting - most of the time, she has a major influence on the overall plot!)

Constructivist ideas, emphasizing the internal processes of the top layer, *underestimate* the influence of the “bottom up” input. This could also be why some cognitive therapies, aiming mainly at the conscious level, are not as effective as one would wish them to be: Talking about depression won’t make it go away; however, sports, aiming at the physical and emotional tiers is much more effective.

Of course, if the flow of information between layers breaks down, circular causality is destroyed, leaving the layers unconnected and thus dysfunctional. But pathologies already arise when the physiological dynamic equilibrium between layers shifts. On the one hand, it is typical for many psychosomatic diseases that a lower tier has spontaneous impact on a higher tier. For example, panic attacks strike, that is, all of a sudden a person is overcome by fear, and a major symptom of schizophrenia is uncontrollable sensory impressions, e.g., voices speaking up, or non-existent persons coming into sight. On the other hand, the influence of the upper layer may be too strong, resulting in obsessive compulsive disorders. For example, anorexia nervosa is characterized by an obsession with controlling the amount of food eaten. Cognitive control is way too strong, overruling the sensation of hunger’s influence on food consumption. Using the metaphor of the self riding a horse, the first class of pathologies is characterized by a mulish horse that time and

again threatens to unsaddle its overchallenged rider, while the second class may rather be characterised by a reckless rider on an overloaded horse. For more psychopathological examples see Kelso and Tognoli (2009), p. 1112.

D) Nature's *bauplan*

In general, we have described and studied multi-layered (hierarchical), dynamical, self-referential and, to a large extent, also self-organizing information-processing systems, situated in a complex environment (see Freeman (1999) for a similar account). A fully functional mind is a well-orchestrated, multi-modular organization; each and every part having its well-defined place and task, and embedded in a multitude of loops. The overall result may be displayed in a single picture:

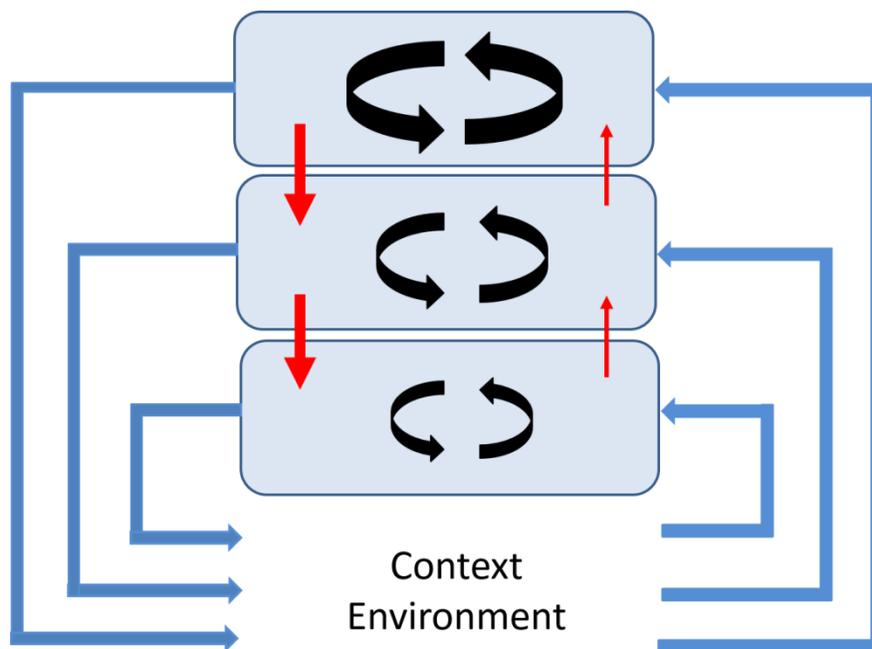


Illustration I18 (A complete multi-layered system with three kinds of feedback loop)

In a nutshell, such a system consists of several layers. The locus of control is towards the top, that is why the internal processes (black arrows) there are more important than those further down. The same holds for the interfaces between the layers (red arrows): The influence “top down” is stronger than the influence “bottom up”, therefore the difference between \downarrow and \uparrow . Moreover, there are sensorimotor loops (blue arrows). That is, all layers may cause actions (left hand side of illustration I18). If a certain action changes the environment of the system this change subsequently alters the sensory input, possibly for all tiers (right hand side of I18).

Note that, given embodiment (implying circularity) and modularity (leading to several tiers), the above construction plan is almost inevitable. These basic boundary conditions imply that successful natural and artificial systems have to be constructed in the way displayed in illustration I18. It is also straightforward that such a system has three major *modi operandi*:

1. Fully aroused (awake), i.e., all three kinds of loop are transmitting large amounts of information. In particular, there is a strong connection between the robot and the external world. For the reasons given in section 1, a human being is ego-conscious in this *modus*, and illustration I17 applies.
2. Asleep (light sleep), i.e., information flows mainly over the black and red pathways, while sensorimotor loops have been largely shut down. Since the distinction between inside and outside does not exist in this *modus*, there can be reality-oriented dreaming, at best, but no clear consciousness. Since the mental system is still connected, various brain regions may interact rather substantially. In particular, information obtained while awake could be incorporated into (cross-areal) neuronal structures.
3. Deep sleep, i.e., with only the black arrows being active, information is mainly processed locally, within layers or modules. Like a shop that closes temporarily, this “fragmented” *modus* allows for major reorganisation and repair, even on an elementary level. Of course, since complex mental functions hinge on connectedness, there is no kind of consciousness in this *modus*.

E) Differentiation and integration

The dynamics of such a system can be characterized by *metastability*. Kelso and Tognoli (2009), pp. 105-108 explain: “One theory stresses that the brain consists of a vast collection of distinct regions ... The other school of thought looks upon the brain not as a collection of specialized centers, but as a highly integrated organ... metastability is an entirely new conception of brain organization ... Individualist tendencies for the diverse regions of the brain to express themselves coexist with coordinative tendencies to couple and cooperate as a whole. In the metastable brain, local and global processes coexist as a complementary pair, not as conflicting theories. Metastability, by reducing the strong hierarchical coupling between the parts of a complex system while allowing them to retain their individuality, leads to a looser, more secure, more flexible form of function ... No dictator tells the parts what to do. Too much autonomy of the component parts means no chance of coordinating them together. On the other hand, too much independence and the system gets stuck, global flexibility is lost.”

Supporting this point of view, Chennu et al. (2014) write: “Theoretical advances in the science of consciousness have proposed that it is concomitant with *balanced cortical integration and differentiation*, enabled by efficient networks of information transfer across multiple scales.” Thus numerical measures of dynamic complexity in general and for consciousness in particular have been proposed (Seth et al. 2011). Kelso and Tognoli (2009), p. 112, conclude “A delicate balance between integration (coordination between individual areas) and segregation (expression of individual behavior) is achieved in the metastable regime ... In a critical range between complete integration and complete segregation, the most favorable situation for cognition is deemed to occur ... measures of complexity reach a maximum when the balance between segregative and integrative forces is achieved.”

Using the idea of differentiation and simultaneous integration opens up another, rather straight, road to self-awareness. In general, starting with a certain structure, new modules may evolve. Typically, they are at first rather primitive but upon elaboration and segregation they obtain a certain “life of their own”. However, since the mental edifice is strongly interconnected, they are also readily integrated into the system already in existence. This happens spontaneously and on all levels:

Given a single sense organ, it is well known that the first tier of sensory cells is occupied with restricted tasks (e.g., the direction of objects) and very limited areas (e.g., a certain spot of the visual field or a certain frequency of sound). Moving up the levels of analysis, the information is integrated, e.g., the areas of the visual field covered get larger and larger. Finally, all unimodal information is integrated into a comprehensive map, i.e., the world as we see, or hear, or smell, or feel it. The next “natural” step, of course, is to integrate all modalities into a comprehensive sensory model of the world, i.e., the world as we see, hear, smell *and* feel it.

Within a sufficiently rich perceptual model of the world, there is a prominent token: The self-image, i.e., a comprehensive map, representing the body in the perceptual realm. Combining this map with all the available information about the (inner) states of the body and motoric agency, readily yields a comprehensive body schema. When vocabulary and its accompanying structure evolve, a new module comes into being – language. Soon, within this area, there is a pronounced token for oneself, the word “I”, say. With the integration of language into the overall system, it is almost inevitable that the new word is connected with the existing body schema (the integrated representative of the entire body so far). This fusion creates a conceptually sharp and stable distinction between oneself and the rest of the world. In other words, distinct self-awareness, an(other) emergent entity, appears, further triggering the drastic effects already described.

This train of thought underlines that it makes sense to distinguish between the protoself, the core self and the extended self, since each of them is located on a different mental tier. However, looking at the structure displayed in the rightmost column of Table T2, these selves also build on

each other. More precisely, as a result of integration, the protoself is an integral part of the core self, the latter being a crucial part of the extended self. Finally, consolidating all available representations yields a single, comprehensive concept of oneself – one’s self, embedded into a larger context (see illustration I17).

On a more abstract level, Juarrero (2009) says: “Dynamical closure always generates a boundary between the new emergent and the background. In the case of autopoietic structures the boundary is self-created by the very dynamics of the system. It can take the form of ... a dynamic phase separation between the emergent structure and the environment, or between the structure and its components.”

F) Universal building blocks

Illustration I18 points out that, despite the nontrivial bauplan, there is a single universal building block, used over and over again: it is the information flow through circuits or *feedback loops*, also called “closed-loop causality” and “circular causality”. This building block appears in various guises:

1. Sensorimotor loops, connecting the outside world with the internal mental life
2. Circuits providing the information interchange between contiguous layers. In IT-jargon, the contiguous upper and lower layers very much act like a client and a server
3. Loops within the tiers and modules, in particular loops serving as interfaces between modules, and loops mediating parts-whole relationships (e.g., between modules and their sub-structures)

Since evolution “likes” to reuse (“re-cycle”) approved building blocks, it is a straightforward conjecture that *all* information processing in natural, self-organizing information systems is heavily based on feedback loops, from the processes within neurons, to small neural nets, neocortical columns, larger modules and networks, cerebral areas, complete functional systems, the integral brain, and – finally -- the whole nervous system.

Moreover, every biological unit, but also every robot, is situated in some context. Thus the very first loop, that is, the elementary sensorimotor loop connecting the “machine” with the outside world, is inevitable. It fits well into our understanding of evolution that this very first loop was re-used, modified (split, differentiated, put to a different use, redirected, strengthened, weakened, dissolved etc.), and gradually extended. Thus creating specialized modules, distinct areas and hierarchic layers, all of them tightly linked, and combined in an overall sound architecture,

“thinking” (more and more sophisticated internal information processing) developed. Finally, well-orchestrated mental edifices with a clear understanding of themselves and their situatedness appeared.

The existing literature places much emphasis on “downward determination” and “circular causality”. According to the reasoning in this article, these terms are important, however, they may also easily miss their target. First, the best formal account of causality is based on directed, *acyclical* graphs (Pearl 2009). Second, although it is correct to acknowledge the role of top-down processes (giving the higher layers at least some influence), one should not overlook the fact that each of them is just a part of more important information-processing loops. The same with the idea of a “closed loop”. Of course, by definition, every loop is closed, i.e., the end-point of some process coincides with its starting point. However, there is also contextual input and procedural output which may be crucial. In this sense, information processing loops are open, they interact massively with one another and their environment. Third, causation and determination are often contrasted with chance and freedom. Since there is an abundance of reasons and causes and since, traditionally, free will has been associated with non-determinism, one is easily led down the primrose path of fundamental discussion.

This author thinks that dynamical system theory should take centre stage, as its emphasis is on the behaviour of complex systems. Thus it is preoccupied with systems being composed of many particles and being held together by “forces” of all kinds. Moreover, context and constraints play a major role, and one has to consider numerous and diverse factors, be they deterministic or stochastic. The modes of such systems range from straightforward convergence, and (quasi-)deterministic behavior to arbitrary random fluctuations with all kinds of regularity and irregularity in-between (e.g., periodicity, more or less stable attractors, turbulence and chaos). There also seems to be self-organized criticality (Èrdi 2008, Sornette 2009, Fingelkurts and Fingelkurts 2013), in particular, when a certain state of mind - in this view a certain attractor - becomes unstable due to saturation, self-amplification (Haykin 2013, p. 442-443) and resonance, e.g., when the best fitting option supersedes all others. Several authors remark that the brain seems to be working “close to instability points” or “at the edge of chaos” (e.g., Chialvo 2007, Legenstein and Maass 2007), when information throughput and complexity are highest. A thought-provoking application of these ideas to our subject can be found in Andrade (2008) who sees a hierarchy of regimes: Physical Information Systems, Information Gathering and Using systems, and Hierarchical Dynamical Information Systems.

What is crucial is the flow of information. This flow is organized in myriads of feedback loops, all of them working simultaneously but at the same time being heavily (hierarchically) interconnected. In the style of Swift’s society of fleas, a loop has smaller loops on which it relies and still larger loops that build on it. In addition, this massively parallel, “Goldilocks-like” - not too tight, not too loose, cf. Juarrero (2009) -, and “metastable” (Kelso and Tognoli 2009,

Fingelkurts and Fingelkurts 2004) processing of information is dynamic: It always changes, never converges or comes to an end. Instead, at any one time, there is some amount of activity which is also variable. However, although the content and the intensity of the internal course of events alter ceaselessly, and, at times, almost unpredictably (e.g., due to new input), the mental stream is kept within certain bounds. In a deep sense, thinking is like (endless) weaving, with elementary mesh loops combining into patches, models and cloth. That's the bottom-up view. However, at the same time there is "downward causation." That is, the whole "loom" (i.e., the entirety of all meshes) and the patterns it produces blaze the trail for subsequent activities on lower tiers.

G) Some maxims

The ultimate challenge consists in building an autonomous machine endowed with a self-extracting multi-layered control system, i.e., to create a mentally developing robot (e.g., Weng 2004, 2007; Cangelosi and Schlesinger 2015). To this end, it seems helpful to ask how nature succeeded in programming its "survival machines" (Dawkins 2006). We have already mentioned her massive parallel approach. Ceaseless as these innumerate processes may be, computation costs time and effort (energy, resources, etc.).

Therefore, a **first maxim** must be to minimize this expense. Haken (2004), p. 17, gives a nice example: "It is often believed that in [the] recognition process an enormous number of details are analysed ... The evolutionary process suggests the opposite." More generally, it seems appropriate only to "think" as much as necessary in order to get a desired result. In other words, elegant solutions restrict central information processing to the inevitable minimum and take advantage of the physics of the body as well as the services of the environment whenever possible. More precisely, nature's economical recipe seems to "shift the computational load from the [central] controller to the morphology and physical properties of the embodiment ... The controller is challenged to maximally exploit the physical peculiarities of the body in its interaction with the environment." (Der and Martius 2011, pp. 29).

Efficient management of a robot uses its scarce resources optimally, that is, it externalizes burdens whenever possible, maximizing the attainable effect but minimizing internal costs. Paradigm examples can be found in Der and Martius (2011). Crucial ideas are collected in Brooks (1999) who underlines that it is embodiment that provides meaning (semantics), that a successful robot needs extensive front and back ends (i.e., powerful sensory and motoric devices), that very often the world is its own best model, and that intelligence is rather determined by the dynamics of the interaction with the world than by explicit representation and reasoning.

The **second maxim** is to start with simple building blocks and to use them time and again, tailoring them to some specific need. Adaptive neural networks, connected by ubiquitous feedback loops embed the individual in the outside world, but also assemble neurons into small, big and huge units – from neocortical columns to brain hemispheres. Although these units' structures cannot be identical – since they have to cope with different problems - they all work on similar principles, and need to be integrated if necessary. For example, it is well known that pattern formation is almost identical to pattern recognition, and similar to decision-making (see numerous references to Haken throughout this contribution). Visual and auditory perception are “a tale of two sides” (Haykin and Chen 2007). Moreover, temporal binding of brain areas always depends on spontaneous synchronization (Fingelkurts and Fingelkurts 2004).

In a nutshell, there are countless neural networks, myriads of modules, and several layers, all acting in parallel and simultaneously. The formidable task of fine-tuning is mostly solved via hierarchic and dynamic self-regulation, channeling the flow of information. Since timing is crucial, so are “spike trains” (Gerstner and Kistler 2002) and their precise synchronization (Haken 2008). Memory is also organized in a unified way, with content being distributed throughout a net of neurons rather than put in a single “drawer” at a particular location. With the information being laid down in the matrix of neuronal connections, memory is dynamic and self-organizing, with some input evoking a certain dynamic response, typically resulting in a fitting output.

In this view, the basic functional unit is a module, i.e., an array of connected neurons. It is rather obvious that such a functional unit can be programmed in two completely different ways: On the one hand, there is “normal” plasticity. Upon gradually strengthening or weakening the connections within this group of neurons, memory or any other function changes slowly. However, on the other hand, there is also “fast learning”, especially during sensitive phases. A plausible mechanism to this end is “massive pruning”, i.e., to start with a large number of neurons and links, and subsequently eliminating most of them during the learning process, resulting in hardware that has been customized quickly to a certain context.

These completely different ways of putting a module into operation may explain the enormous differences upon learning a similar task, e.g., between first and second language acquisition. Thanks to the first maxim, i.e., since it is costly to first build a large field of neurons and then destroy most of it, the later process should be the exception in normal (adult) life. However, when the focus is on rapid development, i.e., in children, the second process should be widespread, and explains in part why they need such an enormous amount of energy to build up their mental edifice.

Since learning is tedious (consuming time and energy), one can also expect that nature uses prior information whenever available. That is, pre-structured neuronal networks, ready-made for a

specific task, should be ubiquitous. On such a basis, learning rather resembles grouting and fine-tuning than a major effort which is inevitable when building a structure from scratch. The example of language acquisition demonstrates the enormous difference: Within a short sensitive phase, children learn to master their mother tongue better than adolescents do a second language. Moreover, hardly any amount of training after the sensitive phase will suffice to reach the level of command a child has obtained in passing.

The **third maxim** is to use self-organization wherever possible. For example, instead of teaching a robot many special tricks or having him store one sensory impression after the other explicitly, it seems much more advisable to compress the necessary information to a bare minimum and re-establish the original when necessary. The popular format MP3 does not store a song completely. Rather, it stores and compresses the information relevant to the human ear, ignoring the remainder. It is also not necessary to save an image completely. Rather, it suffices to retain some particular features and fill in the rest upon request, i.e., given certain clues. The human eye is also not a camera taking picture after picture and combining them into a movie. Rather, elementary saccades look for differences and just update those parts of our view that have changed.

Haken (2006), p. 28, summarises: “Quite often it is assumed that the incoming pattern is compared with templates. However, the storage of a template would require quite a large amount of information. Therefore, one might imagine, in the sense of synergetics, that only specific characteristic features are stored in the form of order parameters which may then be called upon to generate a detailed picture. In this sense then, pattern recognition becomes an active process in which new patterns are formed in a self-organized fashion...”

It may be added that every conventional computer program can be understood as a compact recipe to some end. Upon its execution, that is, upon putting it in a certain environment, it is decompressed and creates all the effects it is supposed to produce. Interestingly enough, Turing showed that very few building blocks (in particular loops and bifurcations) suffice to compute anything that is calculable. Notice the deep-rooted similarity: Computer programs, genes, inseminated egg cells - indeed any kind of offspring - are seeds that, if put into an appropriate context, develop rather automatically, they “unfold” there so to speak. However, self-organization goes much further.

First, due to the permanent feedback of the organism and its environment, self-development is strongly adaptive in the sense that the course of "unfolding" is very much guided by local, specific boundary constraints. For example, given the initial competence of language acquisition, every healthy child is able to learn any language perfectly, just depending on the area where it grows up. In the extreme, the context acts like cladding being filled with the evolving structure.

Second, development is automatic and follows general rules: It always starts with crude, rather rudimentary beginnings, e.g. immature neural equipment. Given a reasonable context, however, humble abilities differentiate into sophisticated ones. An appropriate amount of guidance and protection certainly helps, yet most of the construction work has to be delivered by the developing structure. Moreover, depending on the ability to be acquired, there are more or less restricted time slots. Typically, it is much easier to learn a skill earlier in life, when the brain and the body are “made for” the acquisition of new faculties of all kind. Since abilities typically build on each other, there is also a natural order in which skills should be acquired. It is futile to teach mathematical subtleties when the pupils have not yet understood elementary numbers.

Third, despite all the work that is going on, upon gradually extending the system “loop by loop”, the whole system remains robust. One could call this “self-organized stability.” New modules are established, tested, run in, geared to each other, gradually added to the whole system, and finally used on a regular basis. Again, in a quite self-organized manner, single building blocks form larger structures, until, when the system has matured, all layers are “installed and ready.” Trying to design and implement a complete software edifice for a robot thus seems a hopeless endeavor. Instead, nature chose not to build “Rome” in a day, but to have humble beginnings grow and thrive.

Fourth, with complex dynamic systems come all kinds of emergent phenomena. In particular, larger aggregates attain abilities that their components do not have. For example, single neurons have a very limited behavioral repertoire, yet neuronal nets can store information and compute complex functions. The components of a cell are just biochemistry, yet the cell can replicate, i.e., manufacture a copy. Multicellular organisms can differentiate, forming versatile bodies with astonishing features. Such “phase transitions” when “completely new dimensions” are reached, are not the exception, but the rule. They happen quite often and all of a sudden. The popular idea of *self-organized criticality* (SOC) even suggests that evolving systems may have – or attain - the ability to provoke such “tipping points” (see the vast literature inspired by Bak et al. (1987)). Typically, the new properties are almost unpredictable and, at best, explainable with the wisdom of hindsight. Nevertheless, they may have dramatic consequences. The amazing phenomenon of self-awareness fits perfectly well into this global picture.

(Continued on Part IV)

Article

Roads to Consciousness: Crucial Steps in Mental Development (Part IV)

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Abstract

This contribution explains several “roads to self-awareness”, all of them based on the natural sciences. The first one follows our bio-psychological evolution. The second road starts with the engineer’s point of view and mainly builds on information science and technology, in particular robotics. The third road taken is the most abstract - It exploits complex dynamic systems and their emergent properties. Despite their different origins and methods, these lines of investigation converge. That is, the findings of various fields can be combined into a unified theory of mind and self-awareness, which is the main purpose of this paper. This overall synthesis suggests that the mind results from a multi-hierarchical organizational structure, and self-reflexive flows of information in embodied systems. In addition to this, stable self-awareness appears spontaneously in sufficiently complex robots, when the system’s capability of describing itself crosses the level of conceptually clear information processing (thinking). As an application, one obtains a number of construction principles for mentally developing systems that are explained towards the end of this contribution.

Part IV of this four-part Article includes: 4. Summary; and References.

Keywords: Self-consciousness, self-awareness, free will, dynamic systems, hierarchical systems, language.

4. Summary

It is perhaps worth pointing out that our analysis predicts the possibility of constructing a conscious artifact and outlines some key principles that should constrain its construction (Tononi and Edelman 1998)

In a nutshell, conceptually clear self-awareness, combined with far reaching autonomy, seems to emerge quite straightforwardly in situated, self-referential, multi-layered dynamical information processing systems endowed with a rich perceptual image and a complex language. The details

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may be tricky (at the very least, animal evolution needed aeons to build such a system) and not yet fully understood. However, many crucial concepts and mechanisms already have been detected. The computer sciences and neurosciences, but also psychology, biology, and physics as well as the philosophy of mind all contribute to the understanding of our mental equipment. Although they have different perspectives and use distinct methods, they do not contradict but rather help each other to create a comprehensive picture.

This article has tried to demonstrate that these lines of investigation are converging towards a complete theory of the human self. Even though it has been a long journey, the route travelled can be summarised in a few milestones:

1. **Embodiment.** Fundamentally, it is “no body, never mind” (Damasio 1995). Only with embodiment come situatedness, real-life problems, and the circular flow of information (Thelen and Smith 1994, Brooks 1999, Gallagher 2006, Pfeifer and Bongard 2007).
2. **Feedback loops** are the ubiquitous, versatile and dynamic functional building blocks of all mental life, reused and reshaped by evolution over and over again. Development is due to the body’s permanent active interaction with its environment.
3. **Progressive differentiation and integration.** Piaget’s universal mechanism explains how a modest starting point can develop into a complex mental construction. That is, feedback loops used as “lassos” are able to capture features, insights, and abilities - one by one - resulting in reliable growth, i.e., gradual differentiation within an integrated total system, thus solving the stability-plasticity dilemma (Richardson and Thomas 2008, Smith 2009).
4. **Self-organizing neural networks** are the physical building blocks used by nature. Since, from a computational point of view, recurrent neural networks are immensely powerful (Haykin, Section 15.5.) they are able to support a tremendous mental edifice. Moreover, their repetitive “Goldilocks-like” architecture is adaptive, and spontaneously develops into massively parallel, hierarchical structures (nets, columns, modules, layers etc.).
5. **Evolution toward complexity.** Out of basic sensorimotor loops thus evolved more advanced functions, in particular, associative memory, learning and meta-learning (Haykin 2013, in particular p. 864), abstract knowledge and reasoning (Cangelosi and Schlesinger 2015, Chapter 8), and language (Asada 2015). Schlesinger (2009), p. 192, summarizes: “There is a broad community of researchers who agree that sensorimotor activity is a fundamental starting point for cognition, in general.” Along this track, primitive neuronal networks also became more and more complex, finally forming something like a triune brain (MacLean 1990), consisting of three major tiers: the reptilian complex (being mainly located in the brain stem, controlling homeostasis and generating instincts), the paleo-mammalian complex

(being located in the limbic system, bringing about emotions), and the neomammalian complex (located in the neocortex, and hosting cognition in a broad sense).

6. **Dynamic system theory.** The human brain is the most complex structure known. Therefore, the terms and ideas of dynamical system theory are useful. For example, spontaneous pattern formation is associated with appropriate order parameters, an idea stressed by synergetics. The re-utilization of the same building blocks (neural networks, feedback loops, differentiation and integration) on different scales results in an overall fractal structure. (For a striking example see McClelland and Vallabha (2009), pp. 16.) More generally, since the architecture of many systems is closely related to their purpose (Rubenstein and Rakic 2013), form follows (from) function, or function becomes incarnated structure. Altogether, it is straightforward to conceive of the brain as a self-organized synergetic computer (Kelso 1995, Haken 2004).
7. **Development** also follows the general logic of dynamical system theory, i.e., it is both spontaneous and self-organized (no contradiction). All that is needed is a germ that will “self-inflate” if put in a suitable environment. That is, via permanent interaction such a system will differentiate and move from primitive to complex, thereby reaching a number of “bifurcation points” and passing through a series of critical phases. Quite characteristically, during this process, rather stable stages alternate with rather chaotic transitions, and with every major evolutionary step, the system all of a sudden acquires/demonstrates new, emergent properties, some of them being truly surprising and almost unpredictable (see e.g., Thelen and Smith 1994, Ritter et al. 2011, Cangelosi and Schlesinger 2015, in particular p. 7, and many contributions of Haken).
8. **Representations of oneself.** Due to the multi-layered structure, several sensory-based descriptions of the environment are available. These are integrated into a perceptual “world model”. Owing to circularity, there are also tokens for oneself (one’s body, or at least parts of it) in each of the sensory realms which are integrated into one body image. When combined with motoric agency, they form a complete body schema.
9. With the realm of **language** evolves a second, conceptually precise, description of the world. Moreover, within this realm, there emerges a concept of oneself. There is now a word for myself. Combining this word and the body schema triggers an “autocatalytic reaction” (described in detail in section 1), leading to a complete reorganization of the mental realm with an integrated, conceptually clear token of / for oneself on top (see illustration I17). Thus man has become “ego-conscious”; he has and is a personal self (Saint-Mont 2001). However, due to the multi-layered architecture, several forms of consciousness can be distinguished (Donald 2002, Damasio 2010).

10. Free will and agency. In a dynamic multi-tiered system, the system's hierarchy also serves as a command structure. Thus the uppermost layer becomes the natural locus of control for the whole system which corresponds nicely to the classical view of a rather autonomous personal self, being the charioteer of mind and body.

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